

# **Automatic Memory Management**

CS143

Lecture 17

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# Lecture Outline

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- Why Automatic Memory Management?
- Garbage Collection
- Three Techniques
  - Mark and Sweep
  - Stop and Copy
  - Reference Counting

# Why Automatic Memory Management?

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- Storage management is still a hard problem in modern programming
- C and C++ programs have many storage bugs
  - forgetting to free unused memory
  - dereferencing a dangling pointer
  - overwriting parts of a data structure by accident
  - and so on...
- Storage bugs are hard to find
  - a bug can lead to a visible effect far away in time and program text from the source

# Type Safety and Memory Management

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- Can types prevent errors in programs with manual allocation and deallocation of memory?
  - some fancy type systems (linear types) were designed for this purpose but they complicate programming significantly
- Currently, if you want type safety then you must use automatic memory management

# Automatic Memory Management

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- This is an old problem:
  - studied since the 1950s for LISP
- There are well-known techniques for completely automatic memory management
- Became mainstream with the popularity of Java

# The Basic Idea

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- When an object is created, unused space is automatically allocated
  - In Cool, new objects are created by new X
- After a while there is no more unused space
- Some space is occupied by objects that will never be used again
  - This space can be freed to be reused later

## The Basic Idea (Cont.)

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- How can we tell whether an object will “never be used again”?
  - in general, impossible to tell
  - we will use heuristics
- Observation: a program can use only the objects that it can find:
  - `let x : A ← new A in { x ← y; ... }`
  - After `x ← y` there is no way to access the newly allocated object

# Garbage

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- An object  $x$  is reachable if and only if:
  - a register contains a pointer to  $x$ , or
  - another reachable object  $y$  contains a pointer to  $x$
- You can find all reachable objects by starting from registers and following all the pointers
- An unreachable object can never be used
  - such objects are garbage

# Reachability is an Approximation

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- Consider the program:

```
main() {  
    x ← new A;  
    foo()  
}
```

- The **A** object is dead when calling foo and will never be used.
- But it will not be garbage collected until the program terminates

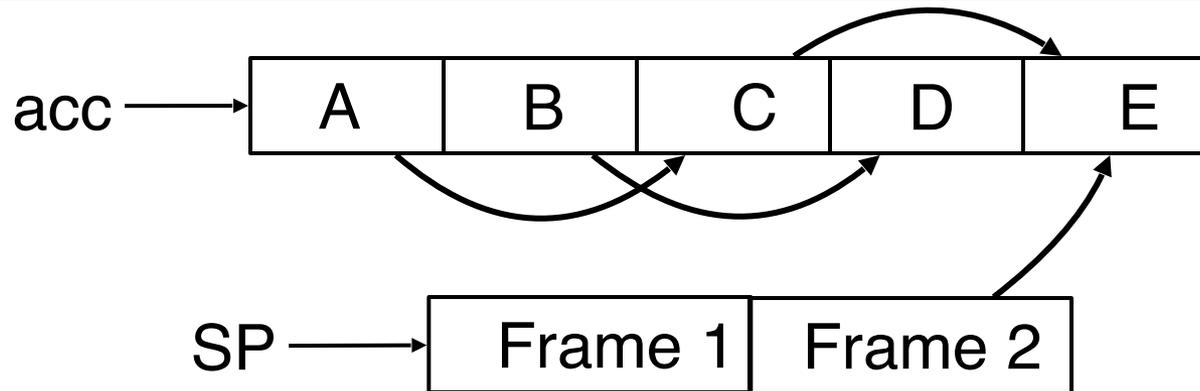
# Tracing Reachable Values in Coolc

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- In coolc, the only registers are the accumulator and the stack pointer
- The accumulator
  - points to an object
  - and this object may point to other objects, etc.
- The stack pointer is more complex
  - each stack frame contains pointers (e.g., method parameters)
  - the stack frames also contain non-pointers (e.g., return address)
  - if we know the layout of the frames we can find the pointers in them

# A Simple Example

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- In Coolc we start tracing from acc and stack
  - These are the roots
- Note B and D are unreachable from acc and stack
  - Thus we can reuse their storage

# Elements of Garbage Collection

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- Every garbage collection scheme has the following steps
  1. Allocate space as needed for new objects
  2. When space runs out:
    - a) Compute what objects might be used again (generally by tracing objects reachable from a set of “root” registers)
    - b) Free the space used by objects not found in (a)
- Some strategies perform garbage collection before the space actually runs out

# Mark and Sweep

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- When memory runs out, GC executes two phases
  - the mark phase: traces reachable objects
  - the sweep phase: collects garbage objects
- Every object has an extra bit: the mark bit
  - reserved for memory management
  - initially the mark bit is 0
  - set to 1 for the reachable objects in the mark phase

# The Mark Phase

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```
let todo = { all roots }
while todo  $\neq \emptyset$  do
  pick  $v \in \text{todo}$ 
  todo  $\leftarrow$  todo - { v }
  if mark(v) = 0 then      (* v is unmarked yet *)
    mark(v)  $\leftarrow$  1
    let  $v_1, \dots, v_n$  be the pointers contained in v
    todo  $\leftarrow$  todo  $\cup$  {  $v_1, \dots, v_n$  }
  fi
od
```

# The Sweep Phase

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- The sweep phase scans the heap looking for objects with mark bit 0
  - these objects were not visited in the mark phase
  - they are garbage
- Any such object is added to the free list
- The objects with a mark bit 1 have their mark bit reset to 0

## The Sweep Phase (Cont.)

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(\* sizeof(p) is the size of block starting at p \*)

p ← bottom of heap

while p < top of heap do

  if mark(p) = 1 then

    mark(p) ← 0

  else

    add block p...(p+sizeof(p)-1) to freelist

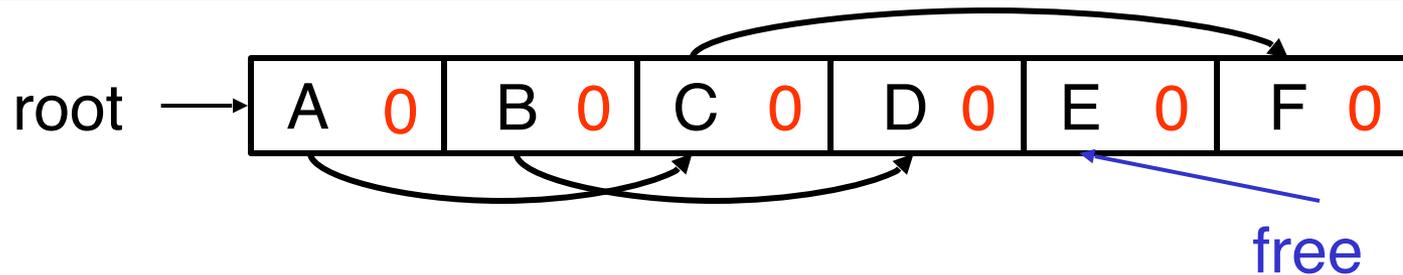
  fi

  p ← p + sizeof(p)

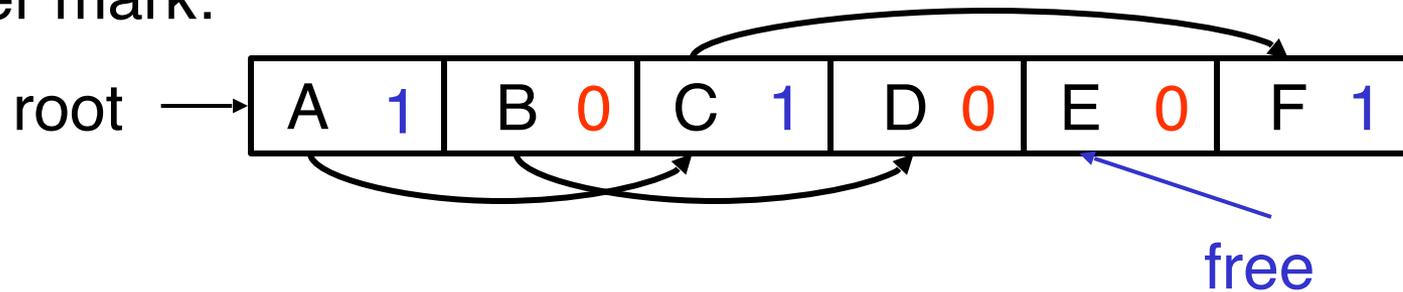
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# Mark and Sweep Example

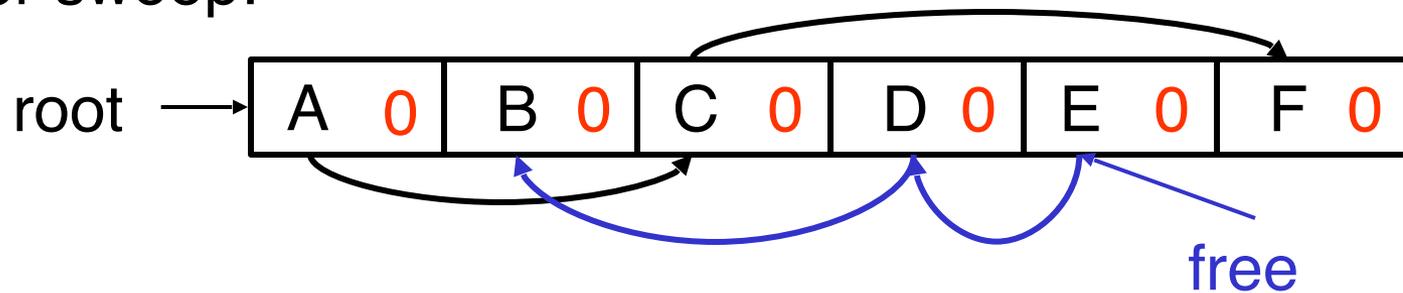
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After mark:



After sweep:



# Details

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- While conceptually simple, this algorithm has a number of tricky details
  - typical of GC algorithms
- A serious problem with the mark phase
  - it is invoked when we are out of space
  - yet it needs space to construct the todo list
  - the size of the todo list is unbounded so we cannot reserve space for it a priori

# Mark and Sweep: Details

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- The todo list is used as an auxiliary data structure to perform the reachability analysis
- There is a trick that allows the auxiliary data to be stored in the objects themselves
  - pointer reversal: when a pointer is followed it is reversed to point to its parent
- Similarly, the free list is stored in the free objects themselves

# Evaluation of Mark and Sweep

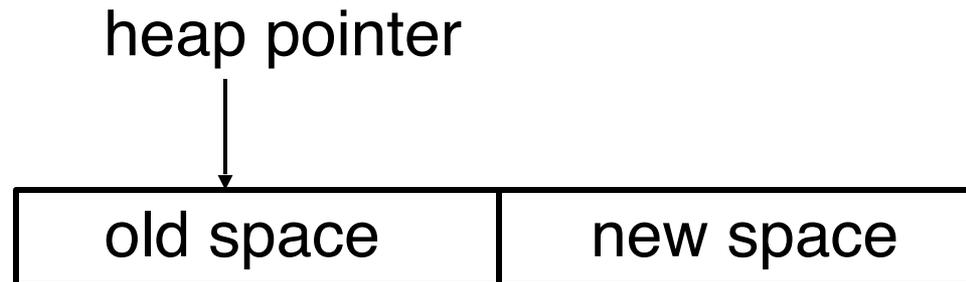
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- Space for a new object is allocated from the free list
  - a block large enough is picked
  - an area of the necessary size is allocated from it
  - the left-over is put back in the free list
- Mark and sweep can fragment the memory
- Advantage: objects are not moved during GC
  - no need to update the pointers to objects
  - works for languages like C and C++

# Another Technique: Stop and Copy

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- Memory is organized into two areas
  - old space: used for allocation
  - new space: used as a reserve for GC



- The heap pointer points to the next free word in the old space
  - allocation just advances the heap pointer

# Stop and Copy Garbage Collection

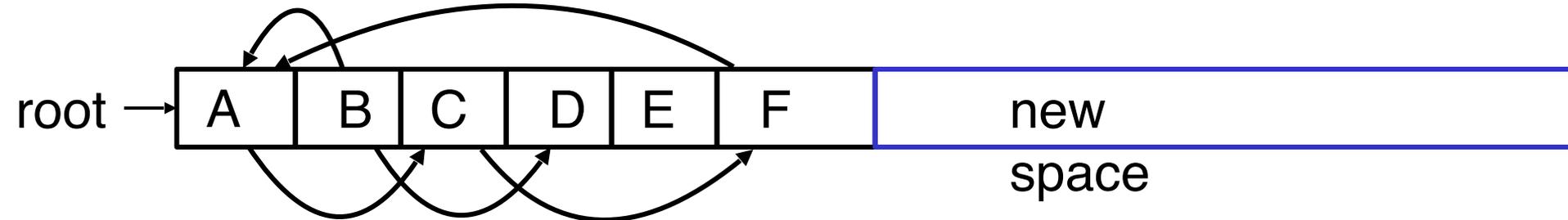
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- Starts when the old space is full
- Copies all reachable objects from old space into new space
  - garbage is left behind
  - after the copy phase the new space uses less space than the old one before the collection
- After the copy the roles of the old and new spaces are reversed and the program resumes

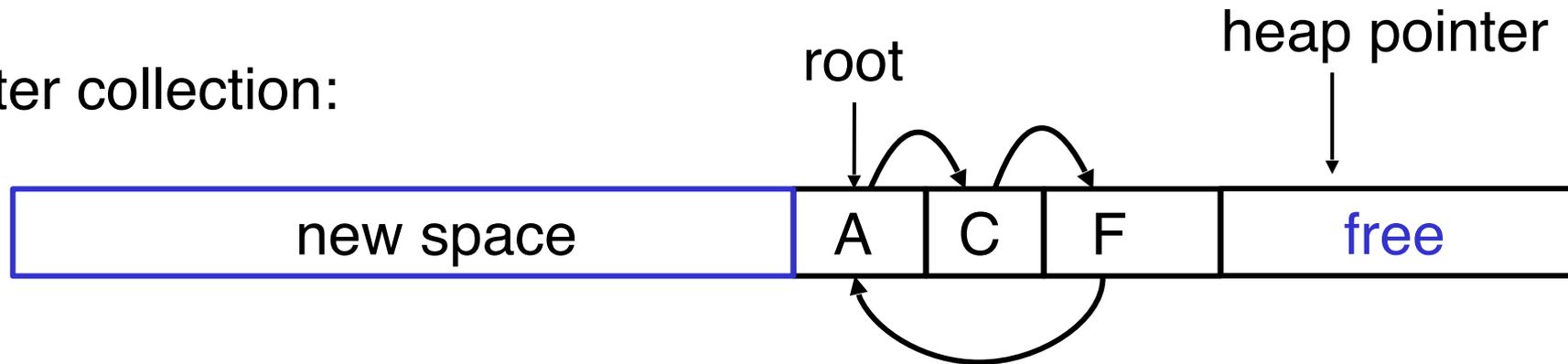
# Example of Stop and Copy Garbage Collection

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Before collection:



After collection:



# Implementation of Stop and Copy

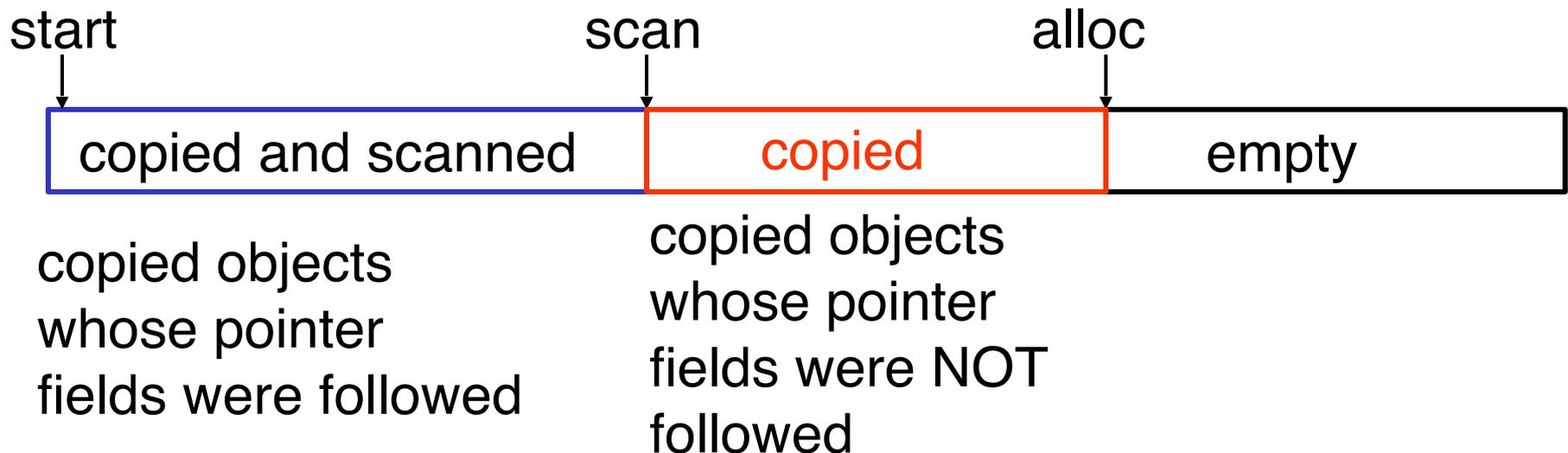
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- We need to find all the reachable objects, as for mark and sweep
- As we find a reachable object we copy it into the new space
  - And we have to fix ALL pointers pointing to it!
- As we copy an object we store in the old copy a forwarding pointer to the new copy
  - when we later reach an object with a forwarding pointer we know it was already copied

# Implementation of Stop and Copy (Cont.)

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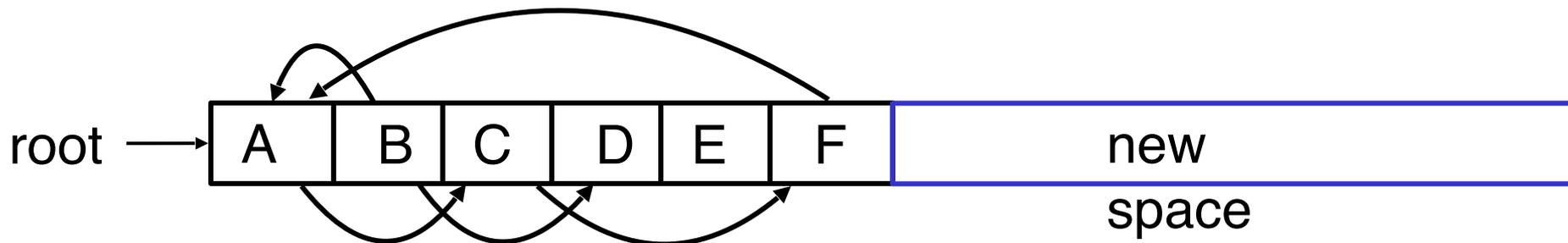
- We still have the issue of how to implement the traversal without using extra space
- The following trick solves the problem:
  - partition the new space in three contiguous regions



# Stop and Copy. Example (1)

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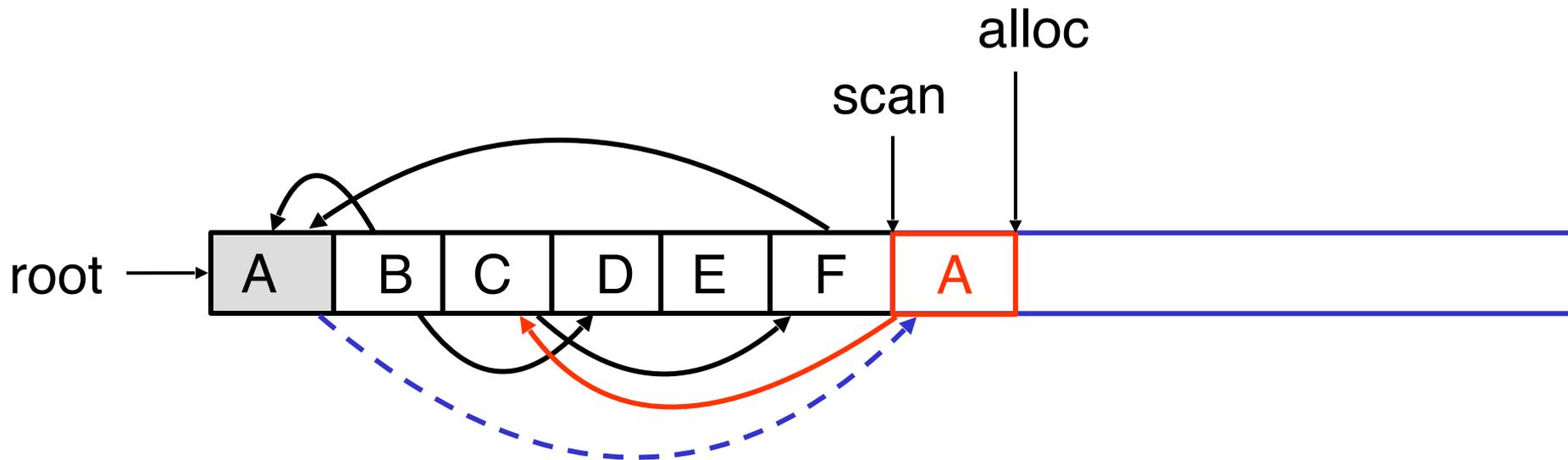
- Before garbage collection



## Stop and Copy. Example (2)

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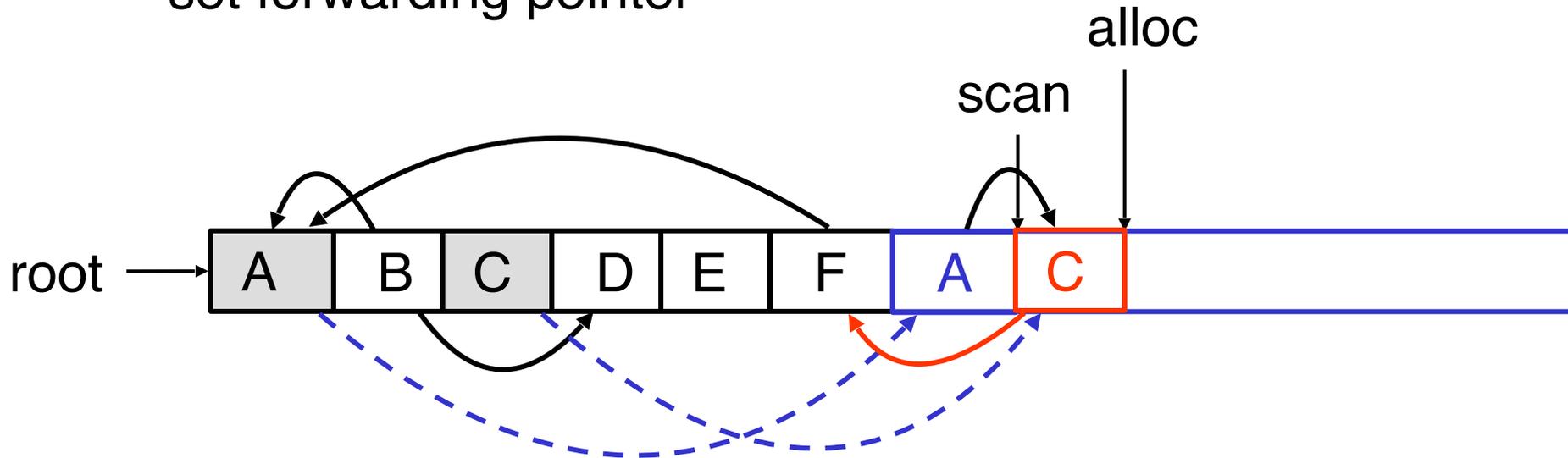
- Step 1: Copy the objects pointed to by roots and set forwarding pointers



## Stop and Copy. Example (3)

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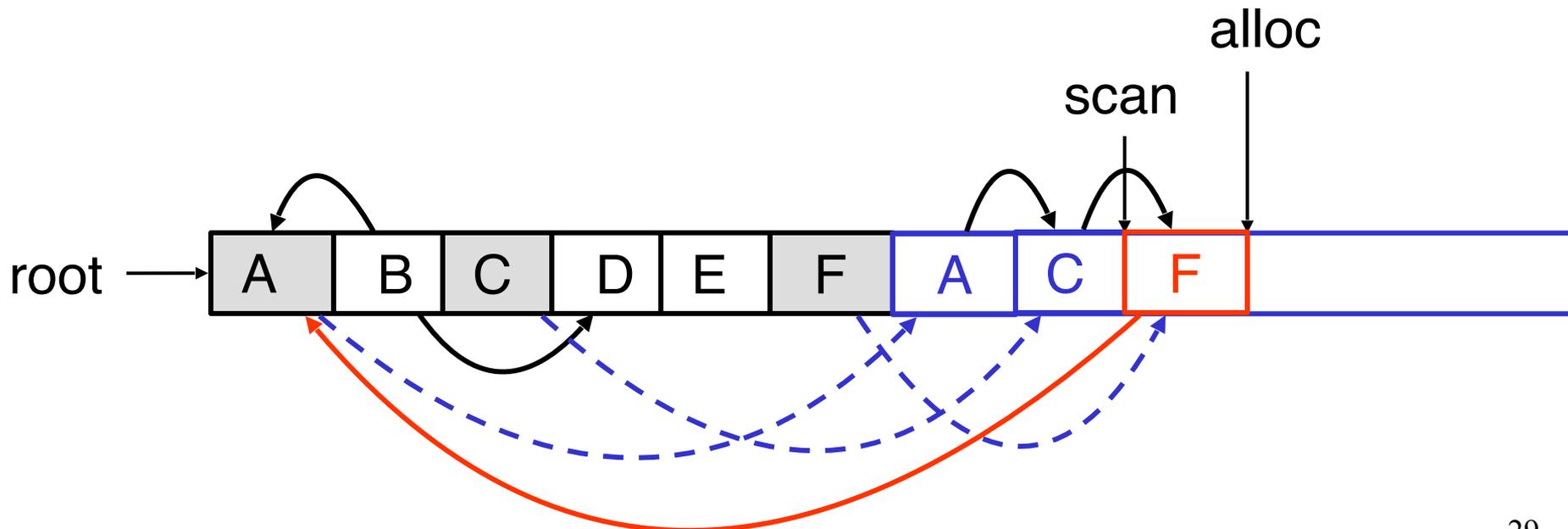
- Step 2: Follow the pointer in the next unscanned object (A)
  - copy the pointed-to objects (just C in this case)
  - fix the pointer in A
  - set forwarding pointer



## Stop and Copy. Example (4)

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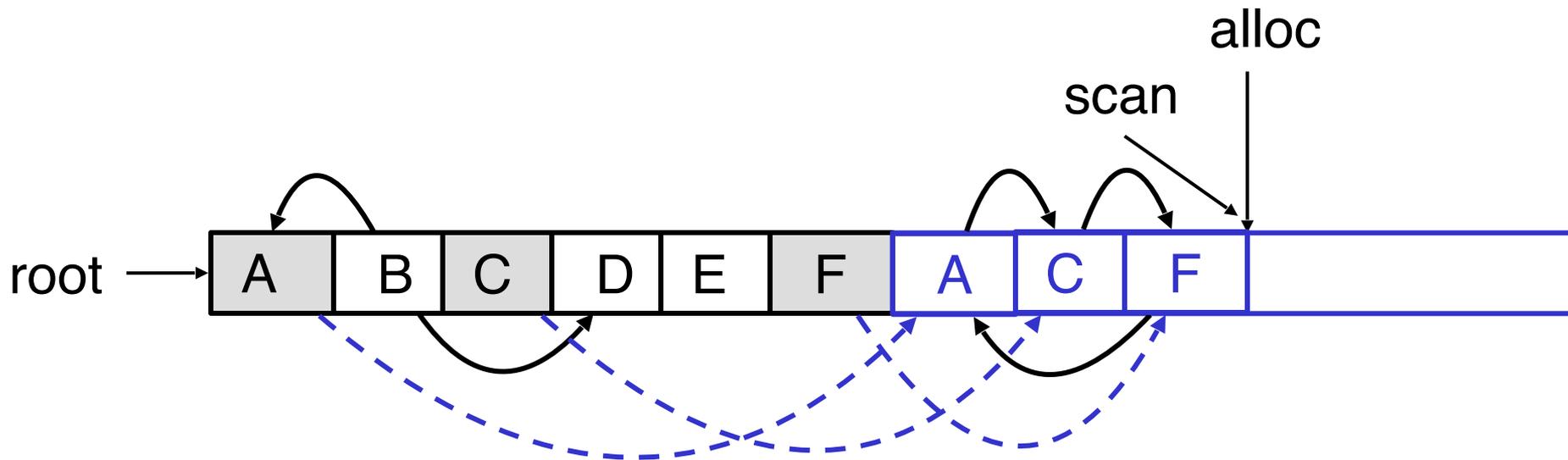
- Follow the pointer in the next unscanned object (C)
  - copy the pointed objects (F in this case)



## Stop and Copy. Example (5)

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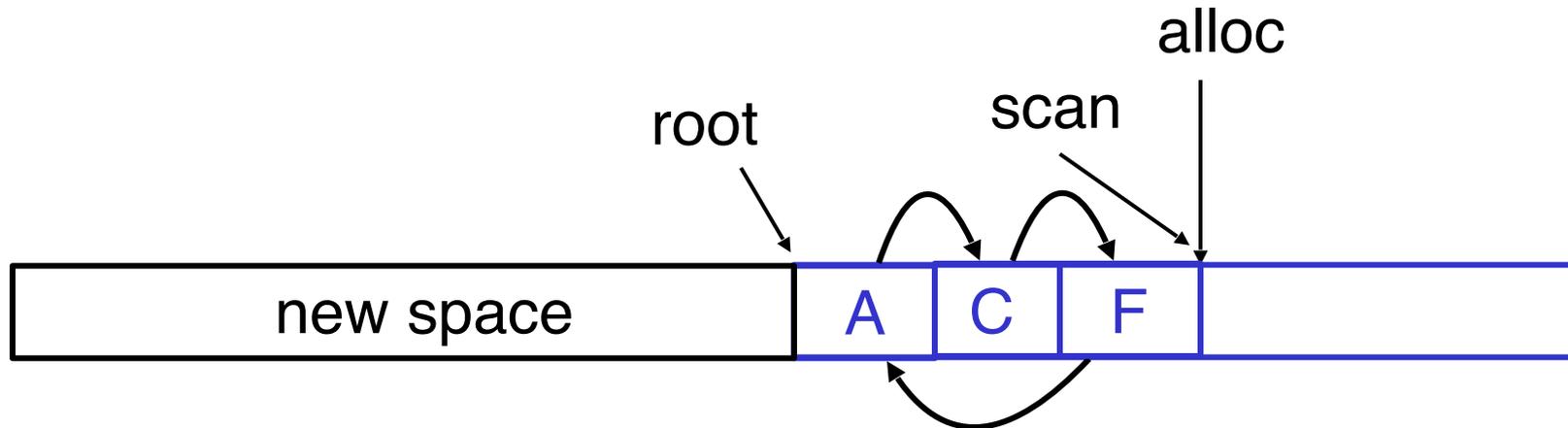
- Follow the pointer in the next unscanned object (F) – the pointed object (A) was already copied. Set the pointer same as the forwarding pointer



## Stop and Copy. Example (6)

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- Since scan caught up with alloc we are done
- Swap the role of the spaces and resume the program



# The Stop and Copy Algorithm

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```
while scan ≠ alloc do
  let O be the object at scan pointer
  for each pointer p contained in O do
    find O' that p points to
    if O' is without a forwarding pointer
      copy O' to new space (update alloc pointer)
      set 1st word of old O' to point to the new copy
      change p to point to the new copy of O'
    else
      set p in O equal to the forwarding pointer
    fi
  end for
  increment scan pointer to the next object
od
```

# Details of Stop and Copy

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- As with mark and sweep, we must be able to tell how large an object is when we scan it
  - and we must also know where the pointers are inside the object
- We must also copy any objects pointed to by the stack and update pointers in the stack
  - this can be an expensive operation

# Evaluation of Stop and Copy

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- Stop and copy is generally believed to be the fastest GC technique
- Allocation is very cheap
  - just increment the heap pointer
- Collection is relatively cheap
  - especially if there is a lot of garbage
  - only touch reachable objects
- But some languages do not allow copying
  - C, C++

# Why Doesn't C Allow Copying?

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- Garbage collection relies on being able to find all reachable objects
  - and it needs to find all pointers in an object
- In C or C++ it is impossible to identify the contents of objects in memory
  - E.g., a sequence of two memory words might be
    - A list cell (with data and next fields)
    - A binary tree node (with left and right fields)
  - Thus we cannot tell where all the pointers are

# Conservative Garbage Collection

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- But it is Ok to be conservative:
  - if a memory word looks like a pointer it is considered a pointer
    - it must be aligned
    - it must point to a valid address in the data segment
  - all such pointers are followed and we overestimate the set of reachable objects
- But we still cannot move objects because we cannot update pointers to them
  - what if what we thought is a pointer is actually an account number?

# Reference Counting

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- Rather than wait for memory to be exhausted, try to collect an object when there are no more pointers to it
- Store in each object the number of pointers to that object
  - this is the reference count
- Each assignment operation manipulates the reference count

# Implementation of Reference Counting

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- new returns an object with reference count 1
- Let  $rc(o)$  be the reference count of  $o$
- Assume  $x, y$  point to objects  $o, p$
- Every assignment  $x \leftarrow y$  must be changed:
  - $rc(p) \leftarrow rc(p) + 1$
  - $rc(o) \leftarrow rc(o) - 1$
  - if( $rc(o) == 0$ ) then mark  $o$  as free
  - $x \leftarrow y$

# Evaluation of Reference Counting

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- Advantages:
  - easy to implement
  - collects garbage incrementally without large pauses in the execution
- Disadvantages:
  - manipulating reference counts at each assignment is very slow
  - cannot collect circular structures

# Evaluation of Garbage Collection

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- Automatic memory management prevents serious storage bugs
- But reduces programmer control
  - e.g., layout of data in memory
  - e.g., when is memory deallocated
- Pauses problematic in real-time applications
- Memory leaks possible (even likely)

# Evaluation of Garbage Collection

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- Garbage collection is very important
- Researchers are working on advanced garbage collection algorithms:
  - concurrent: allow the program to run while the collection is happening
  - generational: do not scan long-lived objects at every collection
  - parallel: several collectors working in parallel