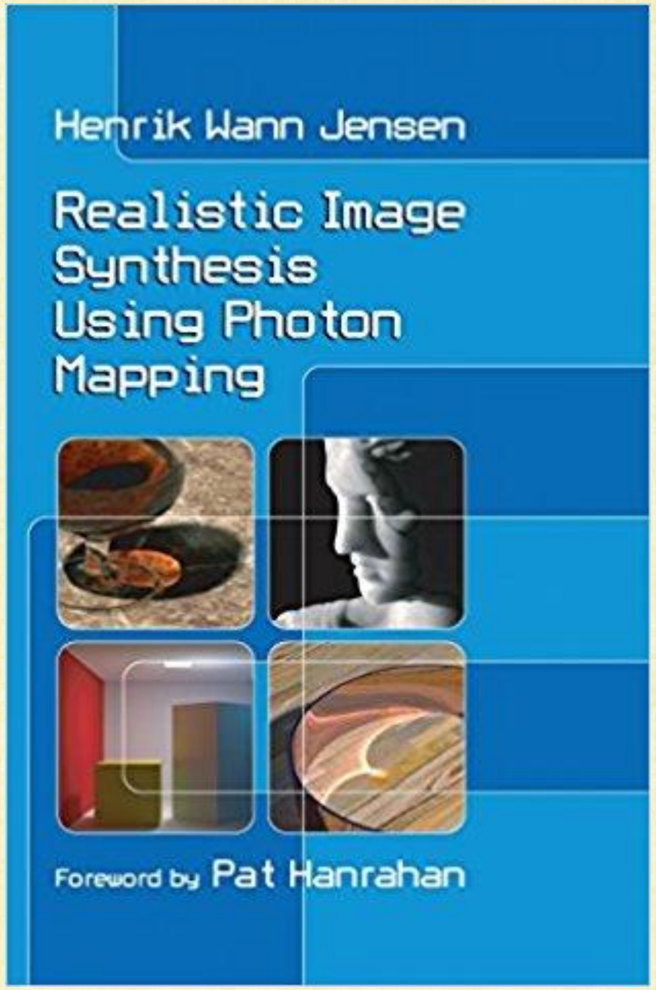
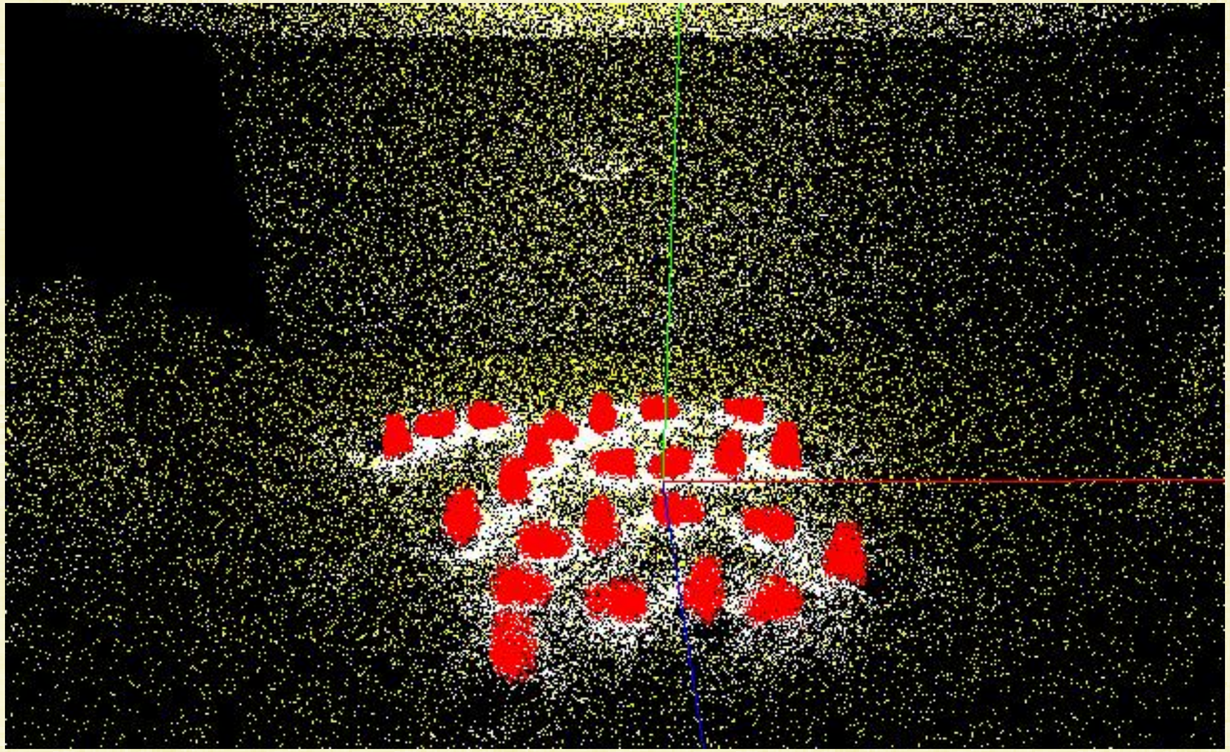
Photon Mapping



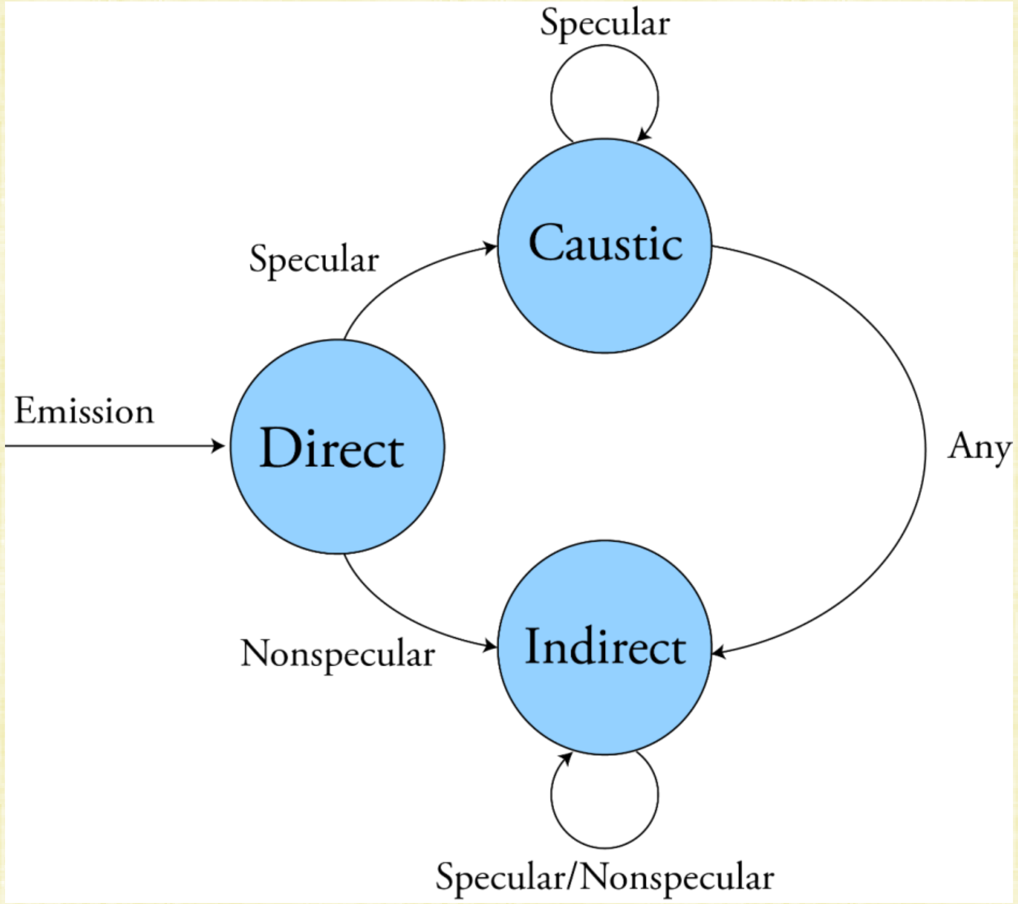
Photon Map (a type of light map)

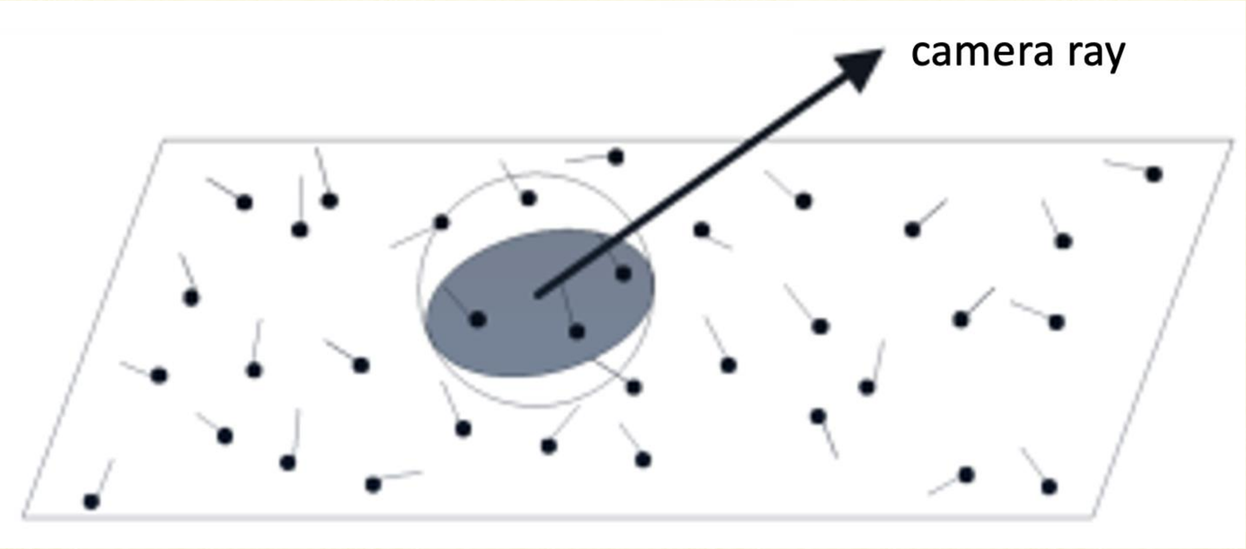
- Photon maps store lighting information on points (“photons”) in 3D space
  - Stored on or near 2D surfaces
- In the last lecture, we (instead) stored information on surface patches



Photon Maps

- Emit photons from light sources and bounce them around the scene, storing light information in the photon map (left image)
- Later (right image), use the photon map to estimate global illumination





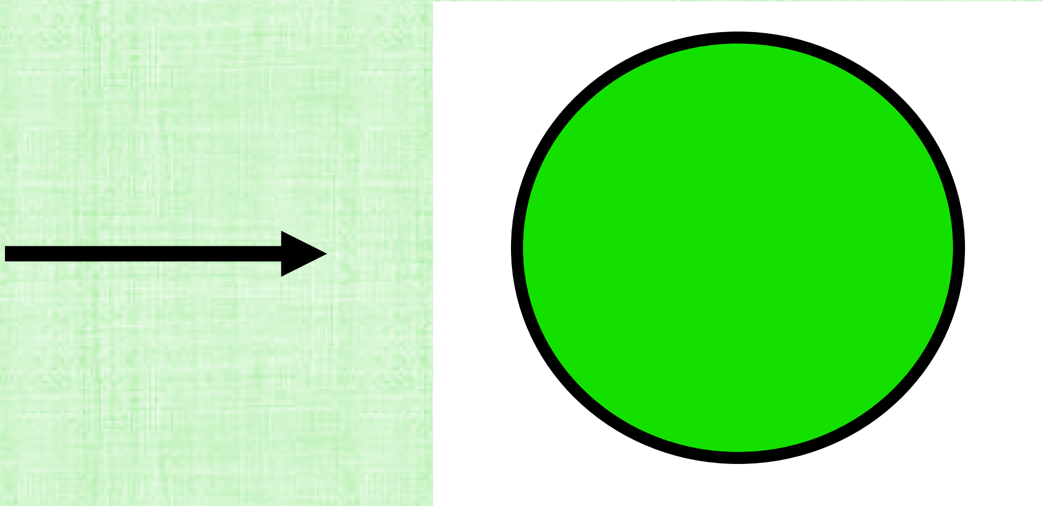
Tractability

- In the last lecture, we discretized surfaces and hemispheres into “chunks”
- This discretization into “elements” is a Newton-Cotes style approximation to the integral
- 2D space + 2D angles = 4D (or 5D for participating media)
- Since Newton-Cotes approaches suffer from the curse of dimensionality, a purely diffuse lighting assumption was used to reduce the dimensionality for the sake of tractability
- Integrating over angles (to obtain radiosity/albedo) reduced the problem to 2D (or to 3D for participating media)
- But direction/angle dependent specular lighting needed to be addressed separately

- Monte Carlo integration (although less accurate than Newton-Cotes) scales well to higher dimensions (i.e., no curse of dimensionality)
- Monte Carlo integration can be used on the full 4D (or 5D) lighting equation
- The purely diffuse lighting assumption is no longer required, and specular lighting can be treated too!

A Simple Example

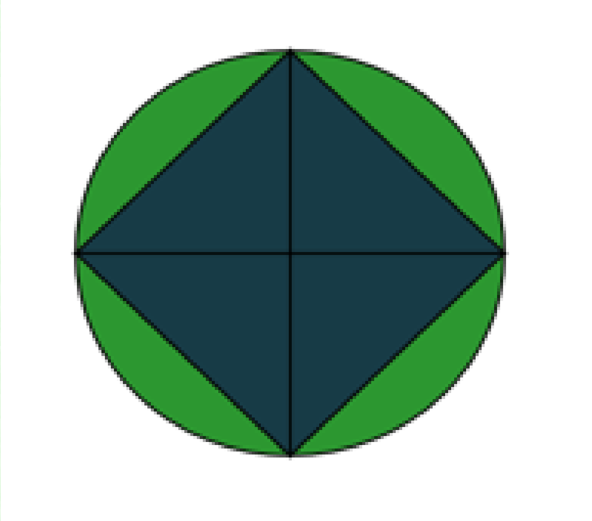
- Consider approximating $\pi = 3.1415926535\ldots$
- Use a compass to construct a circle with radius = 1
- Since $A = \pi r^2$, the area of this unit circle is π
- Integrate $f(x, y) = 1$ over the unit circle to obtain $\iint_A f(x, y)\,dA = \pi$



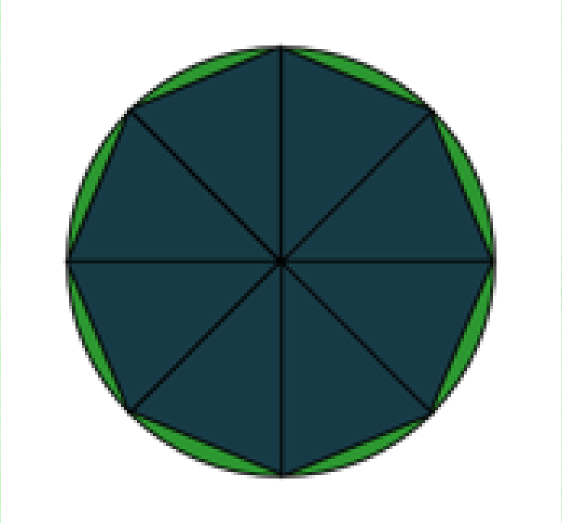
$Area = \pi$

Newton-Cotes Approach

- Inscribe triangles inside the circle
- Sum the area of all the triangles (no need to trivially multiply by the height = 1)
- The difference between the area A and its approximation with triangles leads to errors



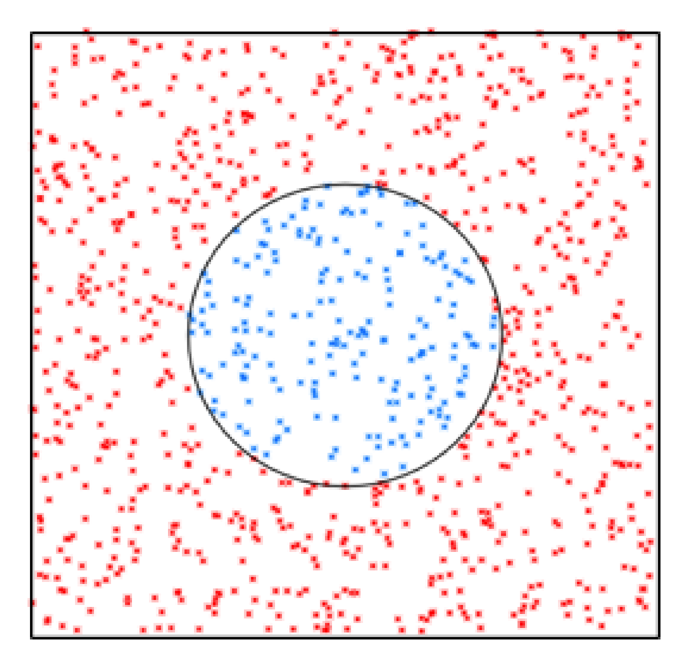
$\pi \approx 2$



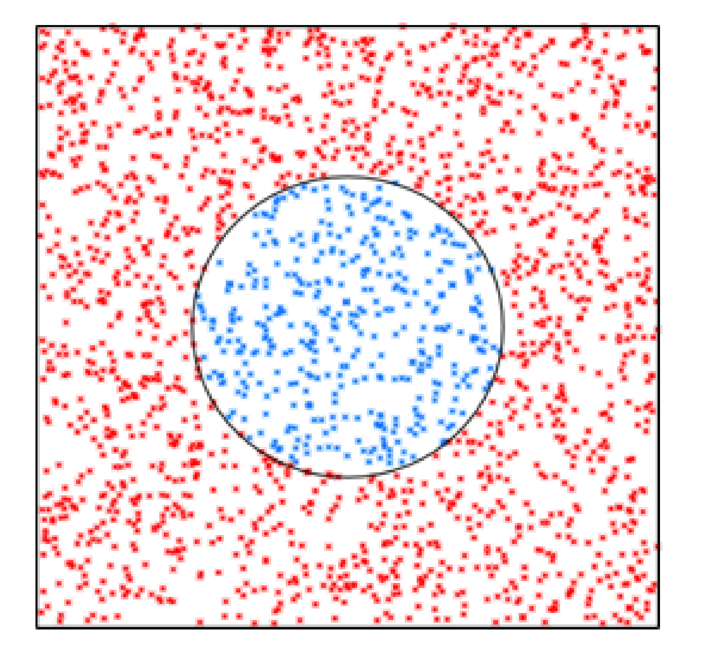
$\pi \approx 2.8284$

Monte Carlo Approach

- Construct a square with side length 4 containing the circle
- Randomly generate N points in the square (color points inside the circle blue)
- Since $\frac{A_{circle}}{A_{box}} = \frac{\pi}{16}$, can approximate $\pi \approx 16\left(\frac{N_{blue}}{N_{blue}+N_{red}}\right)$



$\pi \approx 3.136$



$\pi \approx 3.1440$

Review: Random Numbers

- **Random variables** – expressions whose value is the outcome of a random experiment
- **Sample space** – set of all possible outcomes
- **Probability distribution** - probability $p(x)$ of selecting an outcome x in the sample space
- **Sampling** – selection of a subset of a sample space (valid when it reflects $p(x)$)

- **Pseudo-Random Number Generator** (PRNG) - deterministic algorithm that generates a sequence of quasi-“random” numbers based on an initial **seed** (a starting point in the pre-determined sequence)
  - PRNGs typically generate real numbers between 0 and 1 aiming for equal (**uniform**) probability
  - The ability to uniformly sample from [0,1] enables sampling from other sample spaces that have non-uniform probabilities

see CS109

Monte Carlo Integration

- Typically used in higher dimensions (5D or more)
- Random (pseudo-random) numbers generate sample points that are multiplied by "element size" (e.g. length, area, volume, etc.)
- Error decreases like $\frac{1}{\sqrt{N}}$ where N is the number of samples (only ½ order accurate)
    - E.g. 100 times more sample points are needed to gain one more digit of accuracy

- Very slow convergence, but independent of the number of dimensions!
- Not competitive for lower dimensional problems (i.e., 1D, 2D, 3D), but the only tractable approach for high dimensional problems

Monte Carlo Integration in 1D

- Consider: $\int_a^b f(x)dx$
- Generate N random samples X_i in the interval $[a, b]$
- Estimate the integral via:

$$F_N = \sum_{i=1}^{N} \left(\frac{b-a}{N}\right) f(X_i) = (b-a)\frac{\sum_{i=1}^{N} f(X_i)}{N}$$

- This is a simple averaging of all the sample results

Importance Sampling

(A Trivial) Motivating Case:

- Suppose $f(x)$ is only nonzero in $[a_1, b_1] \subset [a, b]$, i.e. $\int_a^b f(x)\mathrm{d}x = \int_{a_1}^{b_1} f(x)\mathrm{d}x$
- Then, $X_i \notin [a_1, b_1]$ do not contribute to the integral
- Thus, it's more efficient to change $p(x)$ to be a uniform distribution over $[a_1, b_1]$ instead of over all of $[a, b]$
- Conclusion: $p(x)$ should prefer areas with higher contributions to (or higher **importance** to) the integral

General Case:

- Given any $p(x)$ with $\int_a^b p(x)\mathrm{d}x = 1$, estimate the integral via:

$$F_N = \frac{1}{N}\sum_{i=1}^{N} \frac{1}{p(X_i)} f(X_i)$$

- When $p(x) = \frac{1}{b-a}$, i.e. uniform sampling, this reverts to: $F_N = (b-a)\frac{\sum_{i=1}^{N} f(X_i)}{N}$

Importance Sampling (an example)

- Monte Carlo estimates for $\int_0^1 x^2 \mathrm{d}x$ with $N = 100$ samples:

$p(x)$	F_N	Relative Error
1	0.33671	1.01%
$2x$	0.33368	0.105%
$3x^2$	$0.3333\overline{3}$	0.000%

- Typically, the error is lower when $p(x)$ better “resembles” $f(x)$
- So, choose $p(x)$ based on physical/known principles or an approximate solution

- Caution: importance sampling does not necessarily reduce error (and can make errors worse)

Photon Emission

- Choose some number of photons, and divide them amongst the lights based on relative power
  - For efficiency/implementation, every photon has the <u>same strength</u>
  - So, brighter lights emit more (not stronger) photons
- Emission Position:
  - Point light - all photons are emitted from a single point
  - Area light - randomly select a point on the surface to emit each photon from
    - Semi-random: Divide a rectangular light into a uniform 2D grid; emit a set number of photons from each grid cell (randomly choosing the position within a cell)
- Emission Direction:
  - Randomly choose a direction on a sphere, a hemisphere, a subset of the sphere (for spotlights), etc.
- In some cases (e.g. consider the sun), a large number of photons would miss the scene entirely
  - Ignore those photons (never emit them)
  - Restrict the light to an appropriate sub-light
  - Scale down the light’s energy to match that of the sub-light (when dividing up photons)

Creating a Light Map

- Use a ray tracer to trace the photon’s path, until it intersects scene geometry
- Each time a photon intersects geometry, add its data to the light map as **incoming light**
  - Make a copy of the photon’s data to store in the light map
  - Don’t delete the photon, or move it into the light map
  - The photon might still bounce around a bit more (if it doesn’t get absorbed)
- Store (in the light map):
  - The point of impact (a location in 3D space)
  - The incoming direction (the ray direction from the ray tracer)
  - Don’t need to store the energy (since all photons have the same energy)

Absorption

- After storing the photon's data in the light map, determine what happens next:

- Objects absorb some incoming light (which is why they have a color)
- There is a chance that the photon is absorbed:
  - Absorbing a fraction of the photon's energy would lead to unequal energy photons
  - Instead, use the fraction of light energy that would be absorbed to calculate a probability that the (entire) photon is absorbed
- Generate a random number (between 0 and 1), and compare it to the probability of absorption (i.e., use Russian Roulette)
  - If absorbed, the process stops (for this photon)
  - Otherwise, the photon bounces/reflects

Reflection

- Compute a bounce direction by mapping probabilities to BRDF directions
  - E.g. a purely diffuse BRDF has equal probabilities for every hemisphere direction
- Generate a random number, and use it to determine the bounce direction
- Then, use the ray tracer to (again) trace the photon's path

- At the next intersection, (again) store the photon's data in the light map
- Then (once again), check for absorption; if not absorbed, bounce again, etc.

- Use a pre-determined maximum number of bounces (before termination)
  - Can usually be set rather high, as photons typically have a diminishing overall chance of avoiding absorption as the number of bounces increases

Photon Map

Physically Based Rendering by Pharr and Humphreys

Rendered Image

Physically Based Rendering by Pharr and Humphreys

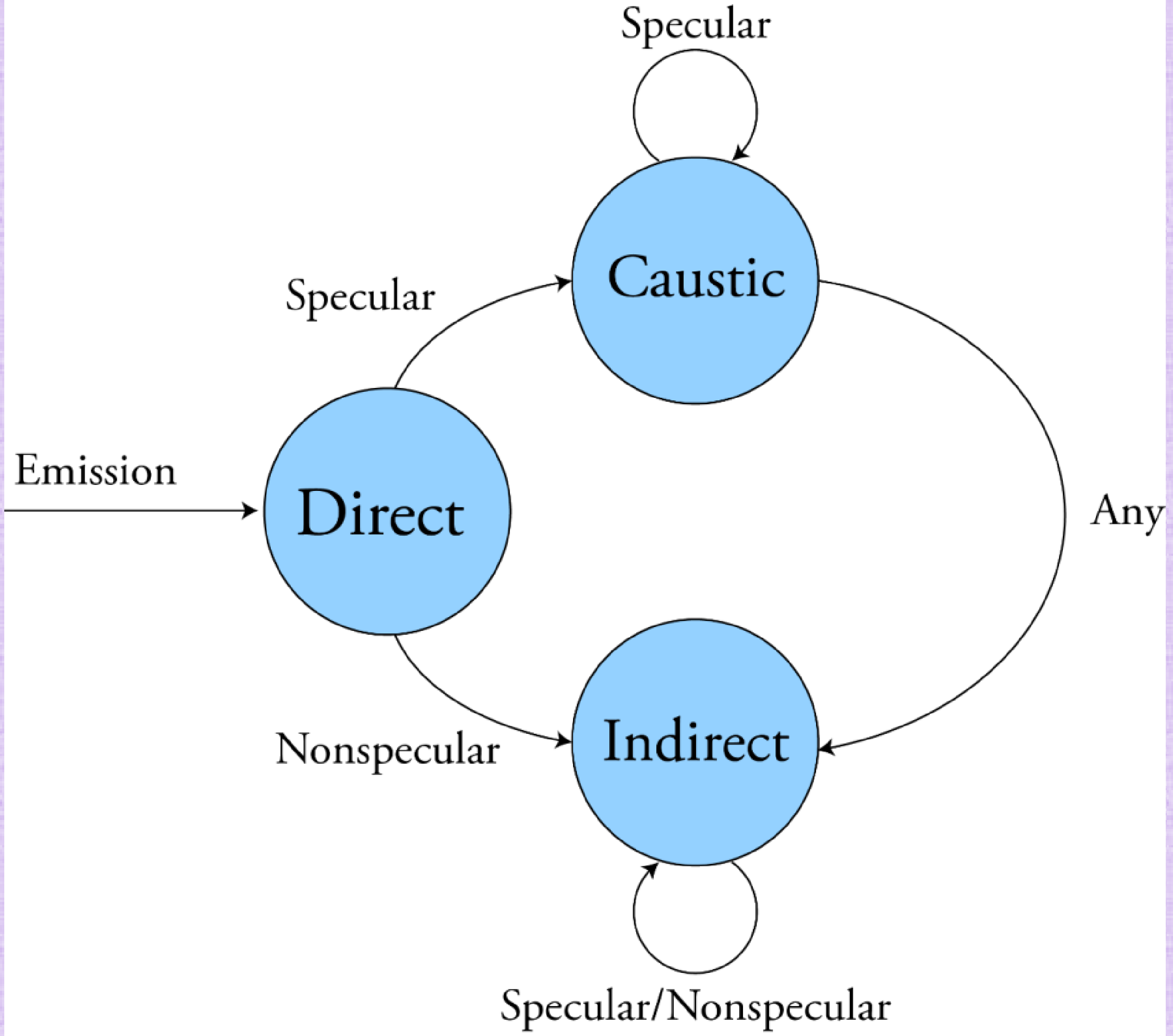
Direct Lighting

- Direct Lighting can be estimated more accurately via shadow rays than via a light map
- So, the first time a photon emitted from a light source hits an object, it is not stored in the light map
  - This is instead accounted for with direct lighting
- Ignoring direct lighting in light maps makes them more efficient, since less information is being stored

Separating Diffuse and Specular

- It’s more efficient to treat diffuse and specular lighting separately
- When bouncing a photon, first determine (randomly) if the photon undergoes:
  - absorption (deleted)
  - or a diffuse bounce
  - or a specular bounce
- The bounce direction is determined randomly (as usual) with the aid of a (diffuse or specular) BRDF
- Two light maps:
  - Caustic Map: stores photons that have had specular bounces only
  - Indirect Lighting Map: for photons that have had at least one diffuse bounce

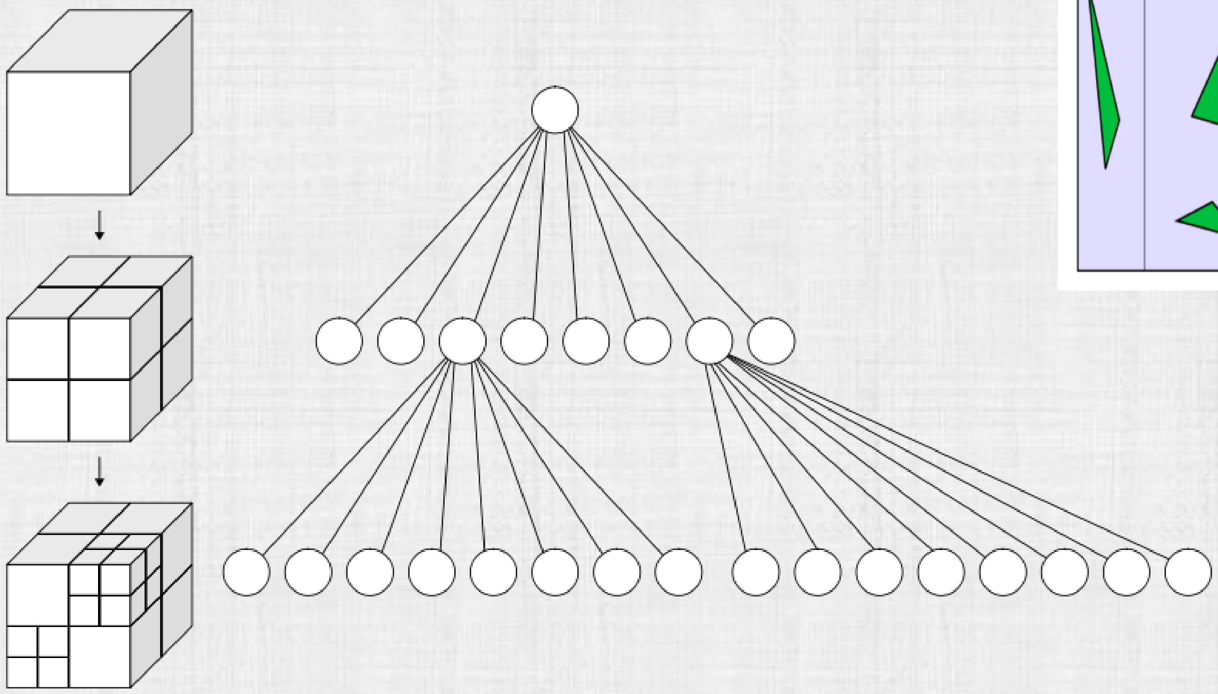
Diffuse/Specular Photon Maps

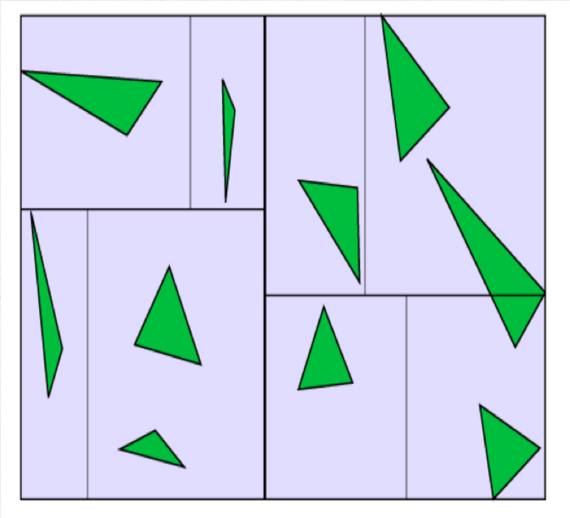


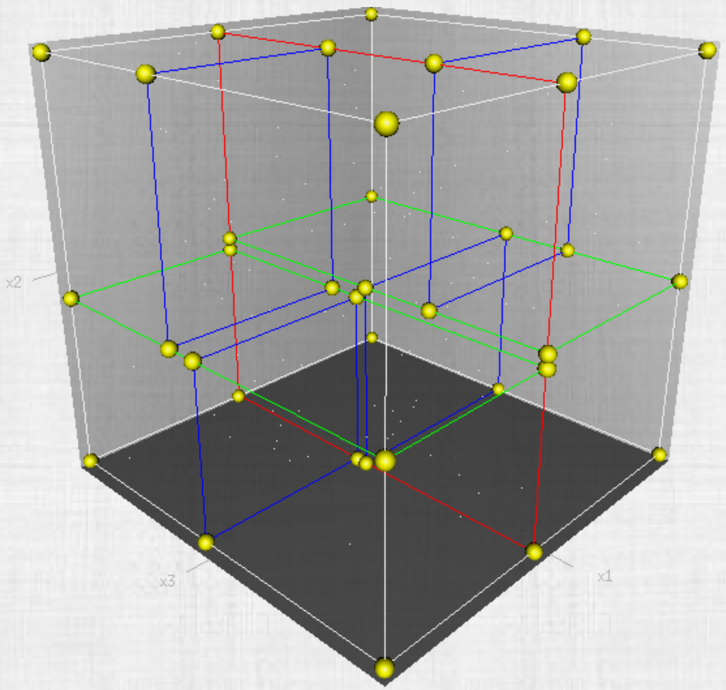
Caustics

Aside: Code Acceleration

- Photons are typically stored in an octree or K-D tree acceleration structure, so that they contain can be retrieved efficiently

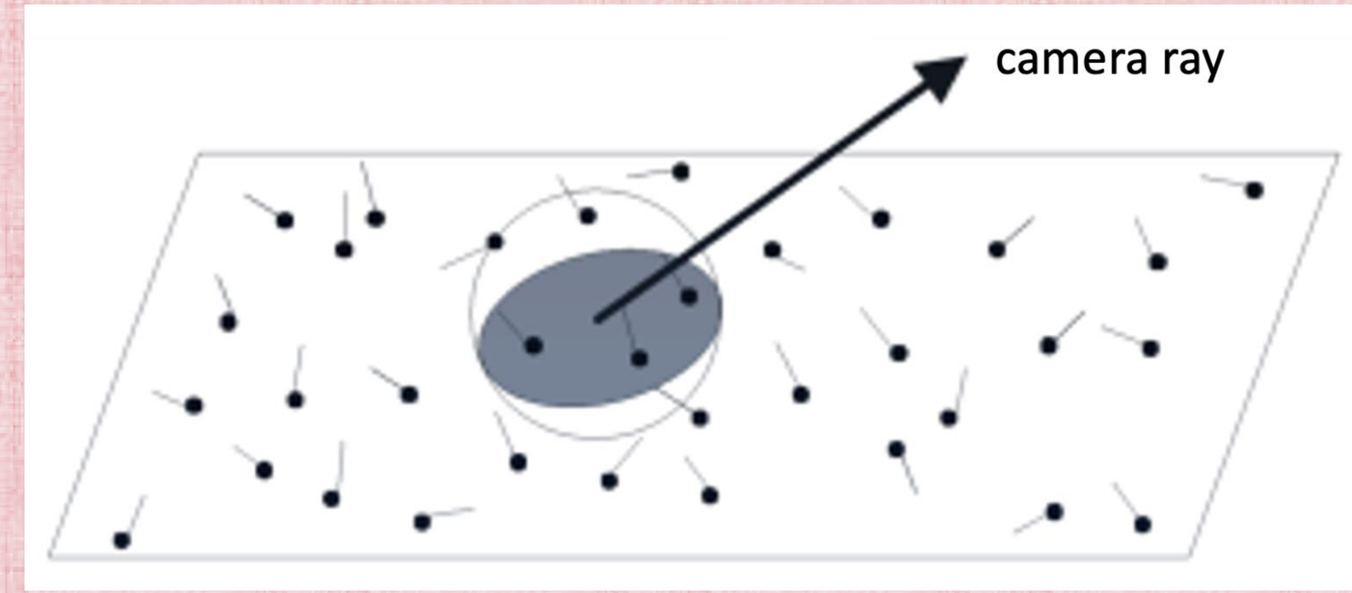






Computing Radiance from the Photon Map)

- Trace rays from the camera and intersect them with objects (as usual)
- Use shadow rays for <u>direct</u> lighting (as usual)
- Estimate the radiance contribution from <u>caustics</u> and <u>indirect</u> lighting using the respective light maps:
  - Use the N closest photons to the point of intersection (found with the aid of an acceleration structure)



Color

- Create 3 photon maps, one for each color channel: Red, Green, Blue
- Objects of a certain color better absorb photons of differing colors, creating differences in the photon maps
- This gives color bleeding and related effects