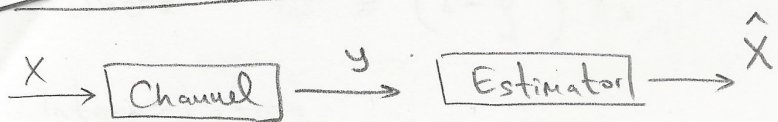


Lecture 15: Estimation



$$f_X(x) f_{Y|X}(y|x)$$

$$f_{X,Y}(x,y)$$

MMSE Estimation: Design the estimator $g: Y \rightarrow X$

s.t. $g(y) = \hat{X}$ that minimizes

$$\mathbb{E}[(X - \hat{X})^2]$$

Optimal Solution: $g(y) = \mathbb{E}[X|Y]$ MMSE Estimator

$$\text{MMSE: } \mathbb{E}[\text{Var}(X|Y)] = \int \text{Var}(X|Y=y) f_Y(y) dy$$

Example: X and Y are jointly Gaussian and zero-mean with covariance

$$K \begin{bmatrix} X \\ Y \end{bmatrix} = \begin{bmatrix} \sigma_X^2 & \text{Cov}(X,Y) \\ \text{Cov}(X,Y) & \sigma_Y^2 \end{bmatrix}$$

We observe Y and want to estimate X .

$$\hat{X} = \mathbb{E}[X|Y] \quad f_{X|Y}(x|y)$$

Last lecture: If X and Y are jointly Gaussian, we

can always write

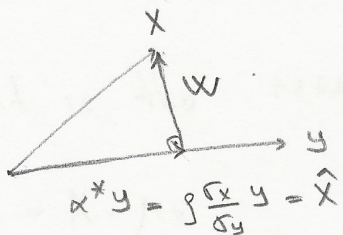
$$X = \alpha^* Y + W$$

If $\alpha^* = \frac{\text{Cov}(X,Y)}{\sigma_Y^2} = \rho \frac{\sigma_X}{\sigma_Y}$ where $\rho = \frac{\text{Cov}(X,Y)}{\sigma_X \sigma_Y}$ Correlation Coefficient

then W is independent of Y and $W \sim \mathcal{N}(0, \sigma_W^2)$

where $\sigma_w^2 = (1-\rho^2) \sigma_x^2$.

Interpretation:



$$\sigma_x^2 = \rho^2 \frac{\sigma_x^2}{\sigma_y^2} \sigma_y^2 + \sigma_w^2$$

$$\sigma_w^2 = (1-\rho^2) \sigma_x^2$$

$$\hat{x} = \mathbb{E}[X|Y] = \rho \frac{\sigma_x}{\sigma_y} y$$

$$\Rightarrow X|Y=y \sim \mathcal{N}\left(\rho \frac{\sigma_x}{\sigma_y} y, (1-\rho^2) \sigma_x^2\right)$$

$$\mathbb{E}[X|Y=y] = \rho \frac{\sigma_x}{\sigma_y} y$$

$$\text{MSE} = \mathbb{E}[\text{Var}(X|Y)]$$

$$= \int \text{Var}(X|Y=y) f_Y(y) dy$$

$$= (1-\rho^2) \sigma_x^2$$

Alternatively,

$$\text{MSE} = \mathbb{E}[(X - \hat{X})^2] = \mathbb{E}[w^2] = \sigma_w^2 = (1-\rho^2) \sigma_x^2$$

$$X = \frac{\alpha^* y}{\hat{X}} + w$$

ension to non-zero mean

X and Y are jointly Gaussian with means μ_x and μ_y respectively and covariance $K \begin{bmatrix} X \\ Y \end{bmatrix} = \begin{bmatrix} \sigma_x^2 & \text{Cov}(X, Y) \\ \text{Cov}(X, Y) & \sigma_y^2 \end{bmatrix}$

What is the MMSE estimate of X from Y ?

$$\tilde{X} = X - \mu_x \quad \tilde{Y} = Y - \mu_y$$

$$\tilde{X} = \alpha^* \tilde{Y} + W \quad \text{where } \alpha^* = \frac{\text{Cov}(\tilde{X}, \tilde{Y})}{\sigma_{\tilde{Y}}^2} = \frac{\text{Cov}(X, Y)}{\sigma_y^2} = \rho \frac{\sigma_x}{\sigma_y}$$

$$\text{where } \rho = \frac{\text{Cov}(X, Y)}{\sigma_x \sigma_y}$$

$$\text{and } W \sim \mathcal{N}(0, (1-\rho^2)\sigma_x^2)$$

$$X - \mu_x = \rho \frac{\sigma_x}{\sigma_y} (Y - \mu_y) + W$$

$$X = \mu_x + \rho \frac{\sigma_x}{\sigma_y} (Y - \mu_y) + W$$

$$\begin{aligned} \hat{X} &= E[X|Y] = E\left[\mu_x + \rho \frac{\sigma_x}{\sigma_y} (Y - \mu_y) \mid Y\right] + \underbrace{E[W|Y]}_{=0} \\ &= \mu_x + \rho \frac{\sigma_x}{\sigma_y} (Y - \mu_y) \end{aligned}$$

$$X|Y=y \sim \mathcal{N}\left(\mu_x + \rho \frac{\sigma_x}{\sigma_y} (y - \mu_y), \sigma_w^2\right)$$

$$E[X|Y] = \mu_x + \rho \frac{\sigma_x}{\sigma_y} (Y - \mu_y)$$

$$\text{MSE} = \sigma_w^2 = (1-\rho^2)\sigma_x^2$$

Example 2 (Special case of Example 1)

$$X \sim \mathcal{N}(0, P)$$

$$Z \sim \mathcal{N}(0, \sigma_z^2)$$

$$\xrightarrow{\oplus} y = X + Z$$

where Z is independent of X

y and X are jointly Gaussian because $\begin{bmatrix} y \\ x \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x \\ z \end{bmatrix}$

$$\hat{X}_{\text{MMSE}} = \mathbb{E}[X|y] = \beta \frac{\sigma_x}{\sigma_y} y = \frac{\sigma_x^2}{\sigma_y^2} y = \frac{P}{P + \sigma_z^2} y$$

$$\beta = \frac{\text{Cov}(X, y)}{\sigma_x \sigma_y} = \frac{\text{Cov}(X, X+Z)}{\sigma_x \sigma_y} = \frac{\sigma_x^2}{\sigma_x \sigma_y} = \frac{\sigma_x}{\sigma_y}$$

$$\text{MMSE} = (1 - \beta^2) \sigma_x^2 = \left(1 - \frac{\sigma_x^2}{\sigma_y^2}\right) \sigma_x^2 = \frac{\sigma_y^2 - \sigma_x^2}{\sigma_y^2} \sigma_x^2$$

$$= \frac{\sigma_z^2 P}{P + \sigma_z^2}$$

$$\begin{array}{lll} \text{if } \sigma_z^2 \rightarrow 0 & \hat{X}_{\text{MMSE}} \rightarrow y & \text{MSE} \rightarrow 0 \\ \sigma_z^2 \rightarrow \infty & \hat{X}_{\text{MMSE}} \rightarrow 0 & \text{MSE} \rightarrow P \end{array}$$

The MMSE estimate balances between prior knowledge and observation.

Non-zero mean. $X \sim \mathcal{N}(\mu_x, P)$ and $Z \sim \mathcal{N}(\mu_z, \sigma_z^2)$

$$\begin{aligned} \hat{X}_{\text{MMSE}} &= \mu_x + \beta \frac{\sigma_x}{\sigma_y} (y - \mu_y) \\ &= \mu_x + \frac{P}{P + \sigma_z^2} (y - \mu_x - \mu_z) \end{aligned}$$

Example 3:

$$X \begin{cases} \rightarrow y_1 = h_1 X + z_1 \\ \rightarrow y_2 = h_2 X + z_2 \\ \rightarrow y_n = h_n X + z_n \end{cases}$$

$$X \sim \mathcal{N}(0, P)$$

$$z_1, z_2, \dots, z_n \sim \mathcal{N}(0, \sigma_z^2)$$

independent of X .

$$\hat{X}_{\text{MMSE}} = \mathbb{E}[X | y_1, y_2, \dots, y_n]$$

$$\hat{X}_{\text{MMSE}} = \mathbb{E}[X | y_1 = y_1, \dots, y_n = y_n]$$

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$$\bar{X} | \bar{y} = \bar{y} \sim \mathcal{N}\left(\mu_{\bar{X}} + K_{\bar{X}\bar{Y}} K_{\bar{Y}}^{-1} (\bar{y} - \mu_{\bar{Y}}), K_{\bar{X}} - K_{\bar{X}\bar{Y}} K_{\bar{Y}}^{-1} K_{\bar{Y}\bar{X}}\right)$$

$$\mathbb{E}[\bar{X} | \bar{y}] = \mu_{\bar{X}} + K_{\bar{X}\bar{Y}} K_{\bar{Y}}^{-1} (\bar{y} - \mu_{\bar{Y}})$$

where $K_{\bar{X}\bar{Y}} = \mathbb{E}[\bar{X}\bar{Y}^T]$

Next setting: Estimate X recursively from

$$y_1, y_2, \dots, y_n$$