

GMINRES or GLSQR?

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Outline

1 Iterative matrix reductions

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- 2 CG-type iterative solvers

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- 4 Numerical results
- 5 Conclusions

Abstract

Given a general matrix A and starting vectors (b, c) , we can construct orthonormal matrices U_k and V_k that reduce A to tridiagonal form: $AV_k \approx U_k T_k$ and $A^T U_k \approx V_k T_k^T$. Saunders, Simon, and Yip (1988) proposed methods for solving square systems $Ax = b$ and $A^T y = c$ simultaneously. The solver USYMQR becomes equivalent to MINRES in the symmetric case with $b = c$.

The method was rediscovered by Reichel and Ye (2006) with emphasis on rectangular systems. For implementation reasons it was regarded as a generalization of LSQR (although it does not reduce to LSQR in any special case). The method has now been applied to two square systems by Golub, Stoll, and Wathen (2007) with focus on estimating $c^T x$ and $y^T b$.

Iterative matrix reductions

- Lanczos 1950 Symmetric
- Arnoldi 1951 Square
- Golub-Kahan 1965 Rectangular
- “New” tridiagonalization 1981–1988, 2006 Rectangular

We call them *processes*

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- Need starting vector $v_1 = b$ (Assume $\|b\| = 1$)

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$$AV_k = V_{k+1}H_k, \quad H_k = \begin{pmatrix} \alpha_1 & \beta_2 & & \\ \beta_2 & \alpha_2 & \beta_3 & \\ & * & * & * \\ & & \beta_k & \alpha_k \\ & & & \beta_{k+1} \end{pmatrix}$$

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$$V_k^T V_k = I \text{ in theory, but at least } \|v_k\| = 1$$

CG-type iterative solvers

for $Ax = b$

- MINRES Lanczos $AV_k = V_{k+1}H_k$
- GMRES Arnoldi $AV_k = V_{k+1}H_k$
- LSQR Golub-Kahan
bidiagonalization $AV_k = U_{k+1}B_k$
 $A^T U_{k+1} = V_k B_k^T + \dots$
- GMINRES?
GLSQR? S-Simon-Yip
bi-tridiagonalization $AV_k = U_{k+1}H_k$
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They all solve $\min \|Xw_k - e_1\|$ and define $x_k = V_k w_k$

$$(X = H_k \text{ or } B_k)$$

MINRES

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Let $x_k = V_k w_k$, where we solve $\min \|H_k w_k - e_1\|$

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- $v_1 = b \Rightarrow$ no need to assume V_k has orthogonal columns

Symmetric \rightarrow Unsymmetric $Ax \approx b$

Lanczos on $\begin{pmatrix} I & A \\ A^T & -\delta^2 I \end{pmatrix} \begin{pmatrix} r \\ x \end{pmatrix} = \begin{pmatrix} b \\ 0 \end{pmatrix}$ (general A)
 with CG-type subproblem gives Golub-Kahan and LSQR

Lanczos on $\begin{pmatrix} & A \\ A^T & \end{pmatrix} \begin{pmatrix} y \\ x \end{pmatrix} = \begin{pmatrix} b \\ c \end{pmatrix}$ (square A)
 is not equivalent to bi-tridiagonalization (but seems worth trying!)

Tridiagonalization of general A using orthogonal matrices

Bi-tridiagonalization

- 1988 Saunders, Simon, and Yip, SINUM 25
 - “Two CG-type methods for unsymmetric linear equations”
 - Focus on square A
 - USYMLQ and USYMQR (GSYMLQ and GMINRES)

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GLSQR
- 2007 Golub, Stoll, and Wathen
“Approximation of the scattering amplitude”
Focus on $Ax = b$, $A^T y = c$
and estimation of $c^T x$, $b^T y$ (without x , y)

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- CG, SYMMLQ, MINRES work well for symmetric $Ax = b$

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- Bi-tridiagonalization of unsymmetric A is no more than twice the work and storage per iteration
- If A is symmetric, we get Lanczos and MINRES etc
- If A is nearly symmetric, total itns should be not much more

Elizabeth Yip's SIAM conference abstract (1982)

CG method for unsymmetric matrices applied to PDE problems

We present a CG-type method to solve $Ax = b$, where A is an arbitrary nonsingular unsymmetric matrix. The algorithm is equivalent to an **orthogonal tridiagonalization** of A .

Each iteration takes more work than the **orthogonal bidiagonalization** proposed by Golub-Kahan, Paige-Saunders for sparse least squares problems (**LSQR**).

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We apply a preconditioned version (Fast Poisson) to the difference equation of unsteady transonic flow with small disturbances. (**Compared with ORTHOMIN(5)**)

Unsymmetric $Ax = b$, $A^T y = c$

Bi-tridiag process starting with (b, c)

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Not much extra effort to get both x_k and y_k

Numerical results with unsymmetric tridiagonalization

Numerical results (SSY 1988)

$$A = \begin{pmatrix} B & -I & & & \\ -I & B & -I & & \\ & \ddots & \ddots & \ddots & \\ & & -I & B & -I \\ & & & -I & B \end{pmatrix}$$

400×400

$$B = \text{tridiag}(-1-\delta \quad 4 \quad -1+\delta)$$

$$20 \times 20$$

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Megaflops to reach $\|r\| \leq 10^{-6} \|b\|$:

δ	0.0	0.01	0.1	1.0	10.0	100.0
ORTHOMIN(5)	0.31	0.57	0.75	0.83	2.55	2.11
LSQR	0.28	1.38	1.48	0.80	0.57	0.27
USYMQR	0.30	1.88	1.98	1.41	0.99	0.64

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Bottom line:

ORTHOMIN sometimes good, can fail. LSQR always better than USYMQR

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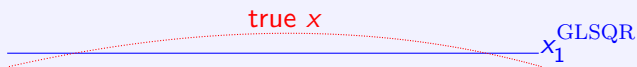
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stopping early
looking at $x_k = (x_{k1} \quad x_{k2} \quad \dots \quad x_{kn})$

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Example 1: We know $x \approx$ **constant**. Choose $c = (1 \quad 1 \quad \dots \quad 1)^T$



Example 2 (Star cluster)

- 256×256 pixels ($n = 65536$), 470 stars

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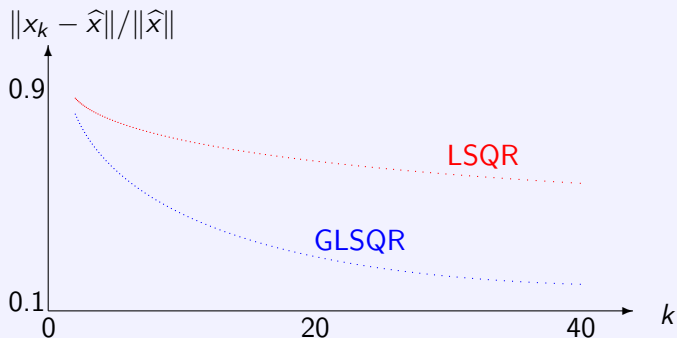
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Conclusions

Subspaces

- **Unsymmetric Lanczos** generates two Krylov subspaces:

$$U_k \in \text{span}\{b \quad Ab \quad A^2b \quad \dots \quad A^{k-1}b\}$$

$$V_k \in \text{span}\{c \quad A^Tc \quad (A^T)^2c \quad \dots \quad (A^T)^{k-1}c\}$$

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- **Bi-tridiagonalization** generates

$$U_{2k} \in \text{span}\{b \quad AA^Tb \quad \dots \quad (AA^T)^{k-1}b \quad Ac \quad (AA^T)Ac \quad \dots\}$$

$$V_{2k} \in \text{span}\{c \quad A^TAc \quad \dots \quad (A^TA)^{k-1}c \quad A^Tb \quad (A^TA)A^Tb \quad \dots\}$$

Functionals $c^T x$, $b^T y$

- Lu and Darmofal (SISC 2003) use **unsymmetric Lanczos with QMR** to solve $Ax = b$ and $A^T y = c$ *simultaneously* and to estimate $c^T x$ and $b^T y$ at a *superconvergent rate*:

$$|c^T x_k - c^T x| \approx |b^T y_k - b^T y| \approx \frac{\|b - Ax_k\| \|c - A^T y_k\|}{\sigma_{\min}(A)}$$

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 - **Matrices, moments, and quadrature**
 - Golub, Minerbo, and Saylor
 - **Nine ways to compute the scattering cross-section**
 - (1): Estimating $c^T x$ iteratively

Block Lanczos

The **Bi-tridiagonalization process** is equivalent to

- **Block Lanczos** on $A^T A$ with starting block $(c \ A^T b)$
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Messages from Marcus Grote (Switzerland) and Yong Sun (China)