## **GMINRES or GLSQR?**

Michael Saunders Systems Optimization Laboratory (SOL) Institute for Computational Mathematics and Engineering (ICME) Stanford University

> Workshop on Matrix Computations in Memory of Professor Gene Golub Institute for Computational Mathematics (ICM) Hong Kong Baptist University





#### Orthogonal matrix reductions

Conclusions

## Outline





## Outline





3 Bi-tridiagonalization of general A

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- 2 MINRES-type solvers
- 3 Bi-tridiagonalization of general A
- 4 Numerical results

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#### Abstract

Given a general matrix A and starting vectors b, c we can construct orthonormal matrices  $U_k, V_k$  that reduce A to tridiagonal form:  $AV_k \approx U_k T_k$  and  $A^T U_k \approx V_k T_k^T$ .

Saunders, Simon, and Yip (1988) proposed methods for solving square systems Ax = b and  $A^Ty = c$  simultaneously. The solver USYMQR becomes equivalent to MINRES in the symmetric case with b = c.

The method was rediscovered by Reichel and Ye (2008) with emphasis on rectangular systems. For implementation reasons it was regarded as a generalization of LSQR (although it does not reduce to LSQR in any special case). The method has been applied to two square systems by Golub, Stoll, and Wathen (2008) with focus on estimating  $c^T x$  and  $b^T y$ .

# **Orthogonal matrix reductions**

Direct: V = product of Householder transformations  $n \times n$ Iterative:  $V_k = \begin{pmatrix} v_1 & v_2 & \dots & v_k \end{pmatrix}$   $n \times k$ Mostly short-term recurrences

Results

Conclusions

#### Tridiagonalization of symmetric A

#### Direct:

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#### Tridiagonalization of symmetric A

#### Direct:

Iterative: Lanczos process

 $\begin{pmatrix} b & AV_k \end{pmatrix} = V_{k+1} \begin{pmatrix} \beta e_1 & T_{k+1,k} \end{pmatrix}$ 

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#### Bidiagonalization of rectangular A

#### Direct:

$$U^{\mathsf{T}}AV = \begin{pmatrix} x & x & & \\ & x & x & \\ & & x & x \\ & & & x \\ & & & x \end{pmatrix}$$

#### Bidiagonalization of rectangular A

#### Direct:

$$U^{T}AV = \begin{pmatrix} x & x & & \\ & x & x & \\ & & x & x \\ & & & x \\ & & & x \end{pmatrix} \qquad U^{T}(b \ A) \ V = \begin{pmatrix} x & x & & \\ & x & x & \\ & & x & x \\ & & & x \\ & & & x \end{pmatrix}$$

#### Bidiagonalization of rectangular A

#### Direct:

Iterative: Golub-Kahan process

$$\begin{pmatrix} b & AV_k \end{pmatrix} = U_{k+1} \begin{pmatrix} \beta e_1 & B_k \end{pmatrix}$$

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Iterative: S-Simon-Yip (1988), Reichel-Ye (2008)

$$\begin{pmatrix} b & AV_k \end{pmatrix} = U_{k+1} \begin{pmatrix} \beta e_1 & T_{k+1,k} \end{pmatrix} \\ \begin{pmatrix} c & A^TU_k \end{pmatrix} = V_{k+1} \begin{pmatrix} \gamma e_1 & T_{k+1,k}^T \end{pmatrix}$$

Conclusions

## **MINRES**-type solvers

based on

#### Lanczos, Arnoldi, Golub-Kahan, bi-tridiag

A	Process			Solver
symmetric	Lanczos	Paige-S	1975	MINRES
rectangular	Golub-Kahan	Paige-S	1982	LSQR
		Fong-S	2011	LSMR
unsymmetric	Arnoldi	Saad-Schultz	1986	GMRES
unsymmetric	bi-tridiag	S-Simon-Yip	1988	USYMQR
rectangular	bi-tridiag	Reichel-Ye	2008	GLSQR

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All methods:

$$\Rightarrow x_k = V_k w_k \text{ where } \min \|\beta e_1 - H_k w_k\|$$

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Symmetric methods for unsymmetric  $Ax \approx b$ 

Lanczos on 
$$\begin{pmatrix} I & A \\ A^T & -\delta^2 I \end{pmatrix} \begin{pmatrix} r \\ x \end{pmatrix} = \begin{pmatrix} b \\ 0 \end{pmatrix}$$
 (general A) gives Golub-Kahan

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Lanczos on 
$$\begin{pmatrix} A \\ A^T \end{pmatrix} \begin{pmatrix} y \\ x \end{pmatrix} = \begin{pmatrix} b \\ c \end{pmatrix}$$
 (square A) is not equivalent to bi-tridiagonalization (but seems worth trying!)

Conclusions

# **Tridiagonalization of general** *A* **using orthogonal matrices**

#### Some history of bi-tridiagonalization

#### • 1988 Saunders, Simon, and Yip, SINUM 25

"Two CG-type methods for unsymmetric linear equations" Focus on square *A* USYMLQ and USYMQR (GSYMMLQ and GMINRES)

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"Approximation of the scattering amplitude"

Focus on Ax = b,  $A^T y = c$  and estimation of  $c^T x$ ,  $b^T y$  (without x, y)

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 2012 Patrick Küschner, Max Planck Institute, Magdeburg Eigenvalues

Need to solve Ax = b and  $A^Ty = c$ 



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- If A is symmetric, we get Lanczos and MINRES etc
- If A is nearly symmetric, total itns should be not much more

## Elizabeth Yip's SIAM conference abstract (1982)

#### CG method for unsymmetric matrices applied to PDE problems

We present a CG-type method to solve Ax = b, where A is an arbitrary nonsingular unsymmetric matrix. The algorithm is equivalent to an orthogonal tridiagonalization of A.

Each iteration takes more work than the orthogonal bidiagonalization proposed by Golub-Kahan, Paige-Saunders for sparse least squares problems (LSQR).

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We apply a preconditioned version (Fast Poisson) to the difference equation of unsteady transonic flow with small disturbances. (Compared with ORTHOMIN(5))

# Numerical results with bi-tridiagonalization

#### Numerical results (SSY 1988)

$$A = \begin{pmatrix} B & -I & & \\ -I & B & -I & & \\ & \ddots & \ddots & \ddots & \\ & & -I & B & -I \\ & & & -I & B \end{pmatrix}$$

$$400 \times 400$$

$$B = \operatorname{tridiag} egin{pmatrix} -1 - \delta & 4 & -1 + \delta \end{pmatrix}$$

20 imes 20

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Megaflops to reach  $||r|| \leq 10^{-6} ||b||$ :

δ	0.0	0.01	0.1	1.0	10.0	100.0
ORTHOMIN(5)	0.31	0.57	0.75	0.83	2.55	2.11
LSQR	0.28	1.38	1.48	0.80	0.57	0.27
USYMQR	0.30	1.88	1.98	1.41	0.99	0.64

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Bottom line:

ORTHOMIN sometimes good, can fail. LSQR always better than USYMQR

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#### Numerical results (Reichel and Ye 2008)

- Focused on rectangular A and least-squares (Forgot about SSY 1988 and USYMQR — hence GLSQR)
- Three numerical examples (all square!)

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For GLSQR, choose  $c = \begin{pmatrix} 1 & 1 & \dots & 1 \end{pmatrix}^T$  because true  $x \approx 100c$ 

#### Example 2 (Star cluster)

- $256 \times 256$  pixels (n = 65536), 470 stars
- Square  $Ax \approx b$ , choose c = b
- Compare error in  $x_k^{\text{LSQR}}$  and  $x_k^{\text{GLSQR}}$  for 40 iterations

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## Conclusions

#### Subspaces

• Unsymmetric Lanczos generates two Krylov subspaces:

$$U_k \in \operatorname{span} \{ b \ Ab \ A^2b \ \dots \ A^{k-1}b \}$$
  
$$V_k \in \operatorname{span} \{ c \ A^{\mathsf{T}}c \ (A^{\mathsf{T}})^2c \ \dots \ (A^{\mathsf{T}})^{k-1}c \}$$

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$$U_k \in \operatorname{span} \{ b \ Ab \ A^2b \ \dots \ A^{k-1}b \}$$
  
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• Bi-tridiagonalization generates

$$U_{2k} \in \operatorname{span} \{ b \ AA^{T}b \ \dots \ (AA^{T})^{k-1}b \ Ac \ (AA^{T})Ac \ \dots \}$$
  
$$V_{2k} \in \operatorname{span} \{ c \ A^{T}Ac \ \dots \ (A^{T}A)^{k-1}c \ A^{T}b \ (A^{T}A)A^{T}b \ \dots \}$$

Reichel and Ye 2008:

Richer subspace for ill-posed  $Ax \approx b$  (can choose  $c \approx x$ )

• Lu and Darmofal (SISC 2003) use unsymmetric Lanczos with QMR to solve Ax = b and  $A^Ty = c$  simultaneously and to estimate  $c^Tx$  and  $b^Ty$  at a superconvergent rate:

$$|c^{\mathsf{T}}x_{k}-c^{\mathsf{T}}x|\approx|b^{\mathsf{T}}y_{k}-b^{\mathsf{T}}y|\approx\frac{\|b-Ax_{k}\|\|c-A^{\mathsf{T}}y_{k}\|}{\sigma_{\min}(A)}$$

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  - Matrices, moments, and quadrature
  - Golub, Minerbo, and Saylor Nine ways to compute the scattering cross-section (1): Estimating c<sup>T</sup>x iteratively

#### Block Lanczos

The bi-tridiagonalization process is equivalent to

• block Lanczos on  $A^T A$  with starting block  $\begin{pmatrix} c & A^T b \end{pmatrix}$ Parlett 1987

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There are two ways of spreading light. To be the candle or the mirror that reflects it. – Edith Wharton



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**MINRES** solvers

**Bi-tridiag** 

Results

Conclusions

#### Gene is with us every day



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