## GMINRES or GLSQR?

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Workshop on Matrix Computations in Memory of Professor Gene Golub Institute for Computational Mathematics (ICM) Hong Kong Baptist University

## Outline

## (1) Orthogonal matrix reductions

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(2) MINRES-type solvers

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(3) Bi-tridiagonalization of general $A$

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(4) Numerical results

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(2) MINRES-type solvers
(3) Bi-tridiagonalization of general $A$
(4) Numerical results
(5) Conclusions

## Abstract

Given a general matrix $A$ and starting vectors $b, c$ we can construct orthonormal matrices $U_{k}, V_{k}$ that reduce $A$ to tridiagonal form: $A V_{k} \approx U_{k} T_{k}$ and $A^{\top} U_{k} \approx V_{k} T_{k}^{\top}$.

Saunders, Simon, and Yip (1988) proposed methods for solving square systems $A x=b$ and $A^{T} y=c$ simultaneously. The solver USYMQR becomes equivalent to MINRES in the symmetric case with $b=c$.

The method was rediscovered by Reichel and Ye (2008) with emphasis on rectangular systems. For implementation reasons it was regarded as a generalization of LSQR (although it does not reduce to LSQR in any special case). The method has been applied to two square systems by Golub, Stoll, and Wathen (2008) with focus on estimating $c^{T} x$ and $b^{T} y$.

## Orthogonal matrix reductions

Direct: $\quad V=$ product of Householder transformations $\quad n \times n$
Iterative: $V_{k}=\left(\begin{array}{llll}v_{1} & v_{2} & \ldots & v_{k}\end{array}\right) \quad n \times k$
Mostly short-term recurrences

## Tridiagonalization of symmetric $A$

## Direct:

$$
V^{T} A V=\left(\begin{array}{ccccc}
x & x & & & \\
x & x & x & & \\
& x & x & x & \\
& & x & x & x \\
& & & x & x
\end{array}\right)
$$

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Direct:
$V^{T} A V=\left(\begin{array}{ccccc}x & x & & & \\ x & x & x & & \\ & x & x & x & \\ & & x & x & x \\ & & & x & x\end{array}\right) \quad V^{T}\left(\begin{array}{cc}0 & b^{T} \\ b & A\end{array}\right) V=\left(\begin{array}{lllll}0 & x & & & \\ x & x & x & & \\ & x & x & x & \\ & & x & x & x \\ & & & x & x\end{array}\right)$

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Iterative: Lanczos process
$\left(\begin{array}{ll}b & A V_{k}\end{array}\right)=V_{k+1}\left(\begin{array}{ll}\beta e_{1} & T_{k+1, k}\end{array}\right)$

## Bidiagonalization of rectangular $A$

Direct:
$U^{T} A V=\left(\begin{array}{ccccc}x & x & & & \\ & x & x & & \\ & & x & x & \\ & & & x & x \\ & & & & x \\ & & & & \\ & & & & \end{array}\right)$

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Iterative: Golub-Kahan process $\quad\left(\begin{array}{ll}b & A V_{k}\end{array}\right)=U_{k+1}\left(\begin{array}{ll}\beta e_{1} & B_{k}\end{array}\right)$

## Tridiagonalization of rectangular $A$

Direct:

$$
U^{T}\left(\begin{array}{cc}
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b & A
\end{array}\right) V=\left(\begin{array}{ccccc}
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Iterative: S-Simon-Yip (1988), Reichel-Ye (2008)

$$
\left.\begin{array}{rl}
(b & A V_{k}
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\beta e_{1} & T_{k+1, k}
\end{array}\right)
$$

# MINRES-type solvers 

based on

Lanczos, Arnoldi, Golub-Kahan, bi-tridiag

MINRES-type solvers for $A x \approx b$

| A | Process |  |  | Solver |
| :--- | :--- | :--- | ---: | :--- |
| symmetric | Lanczos | Paige-S | 1975 | MINRES |
| rectangular | Golub-Kahan | Paige-S | 1982 | LSQR |
|  |  | Fong-S | 2011 | LSMR |
| unsymmetric | Arnoldi | Saad-Schultz 1986 | GMRES |  |
| unsymmetric | bi-tridiag | S-Simon-Yip | 1988 | USYMQR |
| rectangular | bi-tridiag | Reichel-Ye | 2008 | GLSQR |

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All methods:

$$
\left.\begin{array}{rl}
\left(\begin{array}{ll}
b & A V_{k}
\end{array}\right) & =U_{k+1}\left(\begin{array}{ll}
\beta e_{1} & H_{k}
\end{array}\right) \\
b-A V_{k} w_{k} & =U_{k+1}\left(\beta e_{1}-H_{k} w_{k}\right.
\end{array}\right),
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& b-A V_{k} w_{k}=U_{k+1}\left(\beta e_{1}-H_{k} w_{k}\right) \\
& \left\|b-A V_{k} w_{k}\right\| \leq\left\|U_{k+1}\right\|\left\|\beta e_{1}-H_{k} w_{k}\right\| \\
& \Rightarrow \quad x_{k}=V_{k} w_{k} \text { where } \min \left\|\beta e_{1}-H_{k} w_{k}\right\|
\end{aligned}
$$

## Symmetric methods for unsymmetric $A x \approx b$

Lanczos on $\left(\begin{array}{cc}I & A \\ A^{T} & -\delta^{2} I\end{array}\right)\binom{r}{x}=\binom{b}{0}$

## (general $A$ )

 gives Golub-KahanCG-type subproblem gives LSQR MINRES-type subproblem gives LSMR

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CG-type subproblem gives LSQR MINRES-type subproblem gives LSMR

Lanczos on $\left(\begin{array}{ll}A^{T} & A\end{array}\right)\binom{y}{x}=\binom{b}{c} \quad$ (square $A$ )
is not equivalent to bi-tridiagonalization (but seems worth trying!)

# Tridiagonalization of general $A$ using orthogonal matrices 

Some history of bi-tridiagonalization

## Bi-tridiagonalization

- 1988 Saunders, Simon, and Yip, SINUM 25
"Two CG-type methods for unsymmetric linear equations"
Focus on square $A$
USYMLQ and USYMQR (GSYMMLQ and GMINRES)


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"Approximation of the scattering amplitude"
Focus on $A x=b, A^{T} y=c$ and estimation of $c^{T} x, b^{T} y$ (without $x, y$ )


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- 2012 Patrick Küschner, Max Planck Institute, Magdeburg

Eigenvalues
Need to solve $A x=b$ and $A^{T} y=c$

## Original motivation (S 1981)

- CG, SYMMLQ, MINRES work well for symmetric $A x=b$


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- CG, SYMMLQ, MINRES work well for symmetric $A x=b$
- Bi-tridiagonalization of unsymmetric $A$ is no more than twice the work and storage per iteration
- If $A$ is symmetric, we get Lanczos and MINRES etc
- If $A$ is nearly symmetric, total itns should be not much more


## Elizabeth Yip's SIAM conference abstract (1982)

CG method for unsymmetric matrices applied to PDE problems

We present a CG-type method to solve $A x=b$, where $A$ is an arbitrary nonsingular unsymmetric matrix. The algorithm is equivalent to an orthogonal tridiagonalization of $A$.

Each iteration takes more work than the orthogonal bidiagonalization proposed by Golub-Kahan, Paige-Saunders for sparse least squares problems (LSQR).

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We apply a preconditioned version (Fast Poisson) to the difference equation of unsteady transonic flow with small disturbances. (Compared with ORTHOMIN(5))

## Numerical results with bi-tridiagonalization

## Numerical results (SSY 1988)

$$
A=\left(\begin{array}{ccccc}
B & -I & & & \\
-I & B & -I & & \\
& \ddots & \ddots & \ddots & \\
& & -I & B & -I \\
& & -I & B
\end{array}\right) \quad B=\operatorname{tridiag}\left(\begin{array}{lll}
-1-\delta & 4 & -1+\delta) \\
& 400 \times 400 & \\
20 \times 20
\end{array}\right.
$$

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$$

Megaflops to reach $\|r\| \leq 10^{-6}\|b\|$ :

| $\delta$ | 0.0 | 0.01 | 0.1 | 1.0 | 10.0 | 100.0 |
| :--- | ---: | ---: | ---: | ---: | ---: | ---: |
| ORTHOMIN(5) | 0.31 | 0.57 | 0.75 | 0.83 | 2.55 | 2.11 |
| LSQR | 0.28 | 1.38 | 1.48 | 0.80 | 0.57 | 0.27 |
| USYMQR | 0.30 | 1.88 | 1.98 | 1.41 | 0.99 | 0.64 |

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Bottom line:
ORTHOMIN sometimes good, can fail. LSQR always better than USYMQR

## Numerical results (Reichel and Ye 2008)

- Focused on rectangular $A$ and least-squares (Forgot about SSY 1988 and USYMQR - hence GLSQR)
- Three numerical examples (all square!)


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Example $1(A x \approx b$ from Fredholm integral eqn of first kind)


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Example $1(A x \approx b$ from Fredholm integral eqn of first kind)


For GLSQR, choose $c=\left(\begin{array}{llll}1 & 1 & \ldots & 1\end{array}\right)^{T}$ because true $x \approx 100 c$

## Example 2 (Star cluster)

- $256 \times 256$ pixels $(n=65536), 470$ stars
- Square $A x \approx b, \quad$ choose $c=b$
- Compare error in $x_{k}^{\text {LSQR }}$ and $x_{k}^{\text {GLSQR }}$ for 40 iterations


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## Conclusions

## Subspaces

- Unsymmetric Lanczos generates two Krylov subspaces:

$$
\begin{aligned}
& U_{k} \in \operatorname{span}\left\{b \quad A b \quad A^{2} b\right. \\
& V_{k} \in \operatorname{span}\left\{\begin{array}{llll}
c & A^{T} c & \left(A^{T}\right)^{2} c & \ldots
\end{array} A^{k-1} b\right\} \\
& \left.\left(A^{T}\right)^{k-1} c\right\}
\end{aligned}
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\end{array} A^{T}\right)^{k-1} c\right\}\right\}
$$

- Bi-tridiagonalization generates
$U_{2 k} \in \operatorname{span}\left\{b \quad A A^{T} b \ldots\left(A A^{T}\right)^{k-1} b \quad A c \quad\left(A A^{T}\right) A c \quad \ldots\right\}$
$V_{2 k} \in \operatorname{span}\left\{c \quad A^{T} A c \quad \ldots\left(A^{T} A\right)^{k-1} c \quad A^{T} b\left(A^{T} A\right) A^{T} b \quad \ldots\right\}$
Reichel and Ye 2008:
Richer subspace for ill-posed $A x \approx b$ (can choose $c \approx x)$


## Functionals $c^{\top} x, b^{T} y$

- Lu and Darmofal (SISC 2003) use unsymmetric Lanczos with QMR to solve $A x=b$ and $A^{T} y=c$ simultaneously and to estimate $c^{T} x$ and $b^{T} y$ at a superconvergent rate:

$$
\left|c^{T} x_{k}-c^{T} x\right| \approx\left|b^{T} y_{k}-b^{T} y\right| \approx \frac{\left\|b-A x_{k}\right\|\left\|c-A^{T} y_{k}\right\|}{\sigma_{\min }(A)}
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$$

- Golub, Stoll and Wathen (2008) use bi-tridiagonalization with GLSQR to do likewise
- Matrices, moments, and quadrature
- Golub, Minerbo, and Saylor

Nine ways to compute the scattering cross-section
(1): Estimating $c^{\top} x$ iteratively

## Block Lanczos

The bi-tridiagonalization process is equivalent to

- block Lanczos on $A^{T} A$ with starting block ( $c A^{T} b$ ) Parlett 1987


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- block Lanczos on $A^{T} A$ with starting block ( $\left.c A^{T} b\right)$ Parlett 1987
- block Lanczos on $\left(A^{T} \begin{array}{ll}A\end{array}\right)$ with starting block $\left(\begin{array}{ll} & b \\ c & \end{array}\right)$ Golub, Stoll, and Wathen 2008


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- block Lanczos on $A^{T} A$ with starting block ( $c A^{T} b$ ) Parlett 1987
- block Lanczos on $\left(A^{T} \begin{array}{ll}A \\ A^{\prime}\end{array}\right)$ with starting block $\left(\begin{array}{ll} & b \\ c & \end{array}\right)$ Golub, Stoll, and Wathen 2008

There are two ways of spreading light.
To be the candle or the mirror that reflects it.

- Edith Wharton


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## Gene is with us every day



